



Towards Realizing Autonomous Driving Based on Distributed Decision Making for Complex Urban Environments

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on behalf of Prof. Dr. Dr. h.c. Sahin Albayrak

Driving in a Digitized City Digital Mobility – Our vision

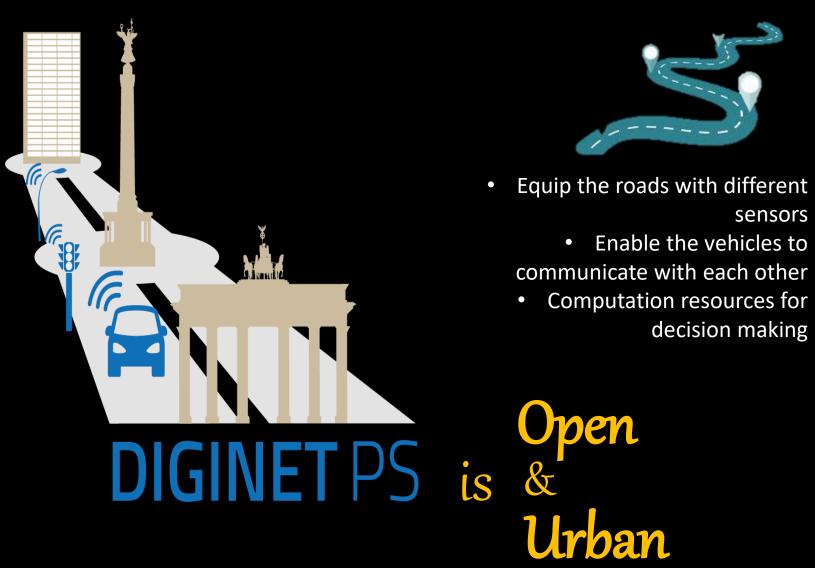
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DIGINET PS

Intelligent vehicle is good ... But Intelligent environment is better ...

Driving in a Digitized City Digital Mobility – Our vision

Make the road talk to vehicles





sensors

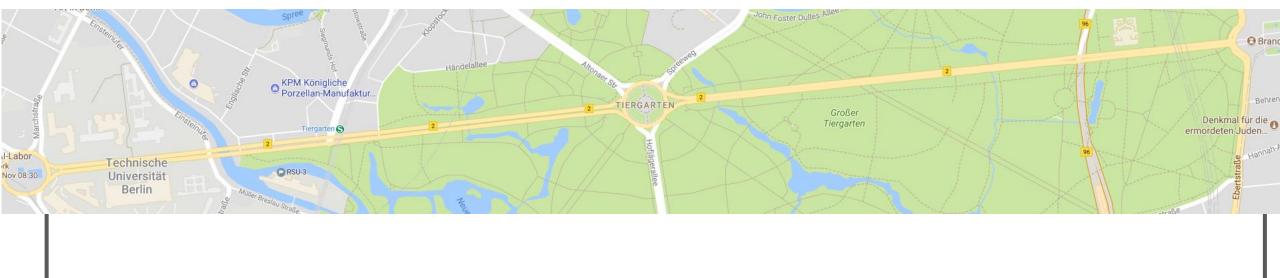
decision making



- Vehicles equipped with different sensors
- Decision logics for assistance \bullet system
- Communication \bullet mechanisms

DigiNet-PS Aims at Achieving ...

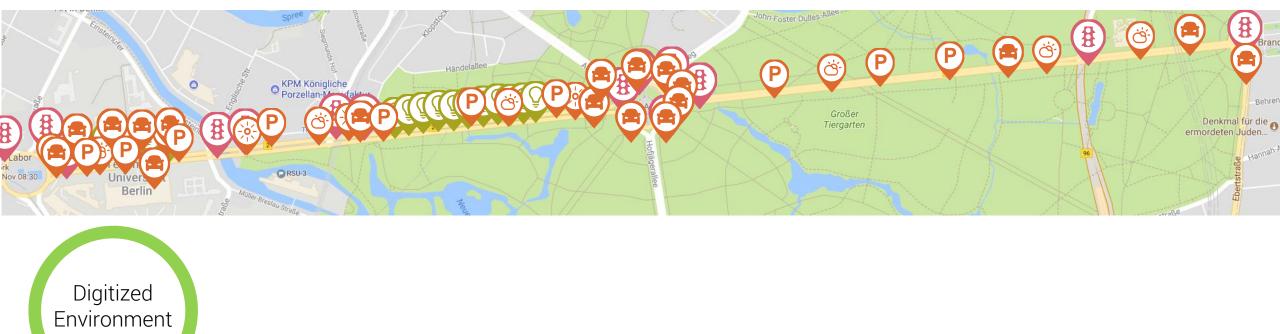
> Open & Distributed Intelligent Solutions for Autonomous Driving in Urban Environment



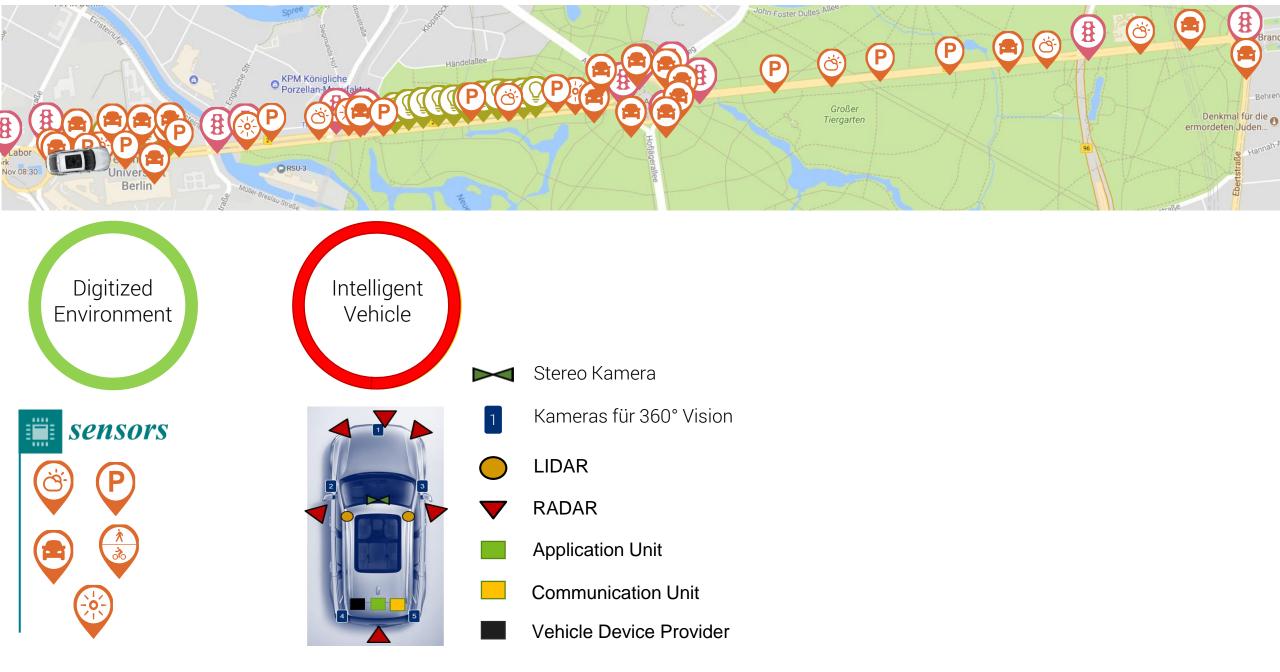
Ernst-Reuter-Platz

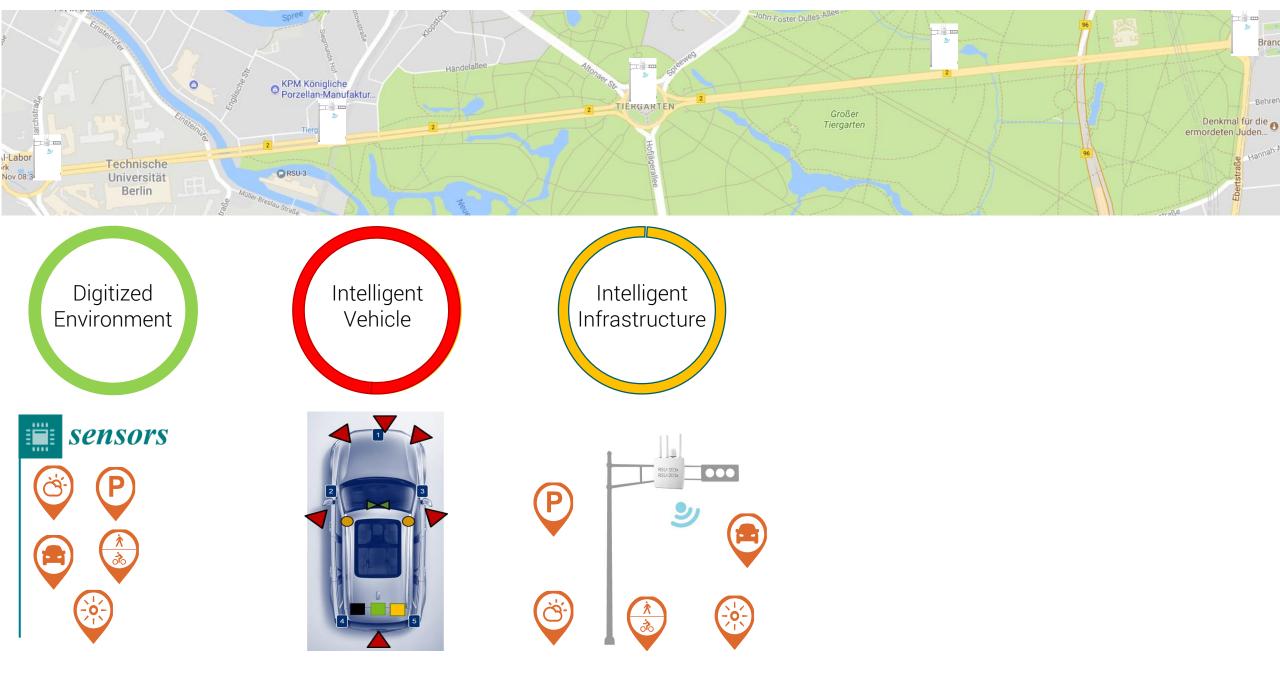
Brandenburger Tor

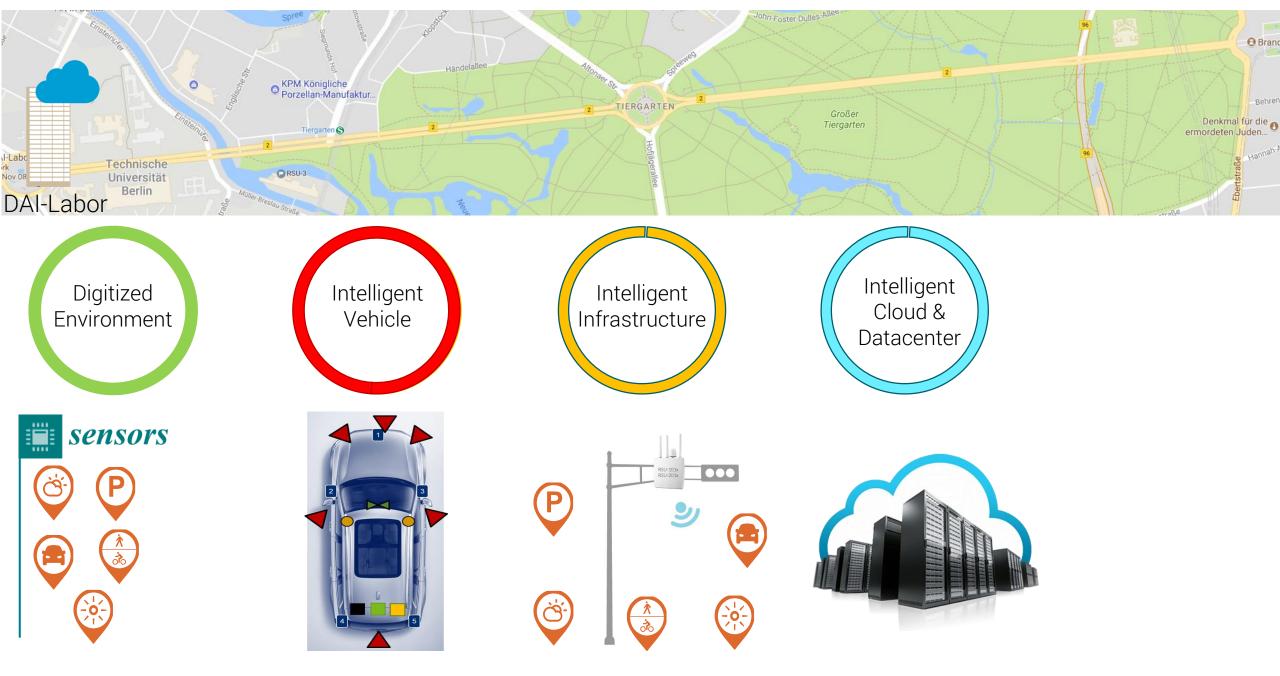
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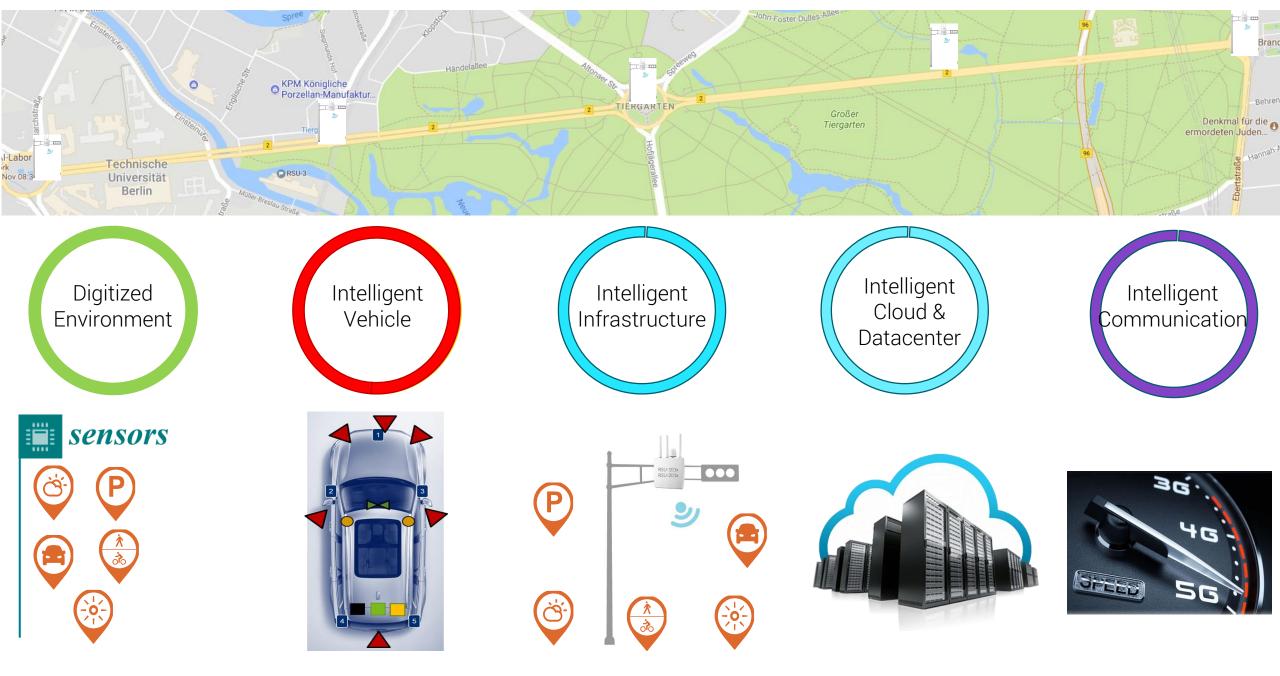




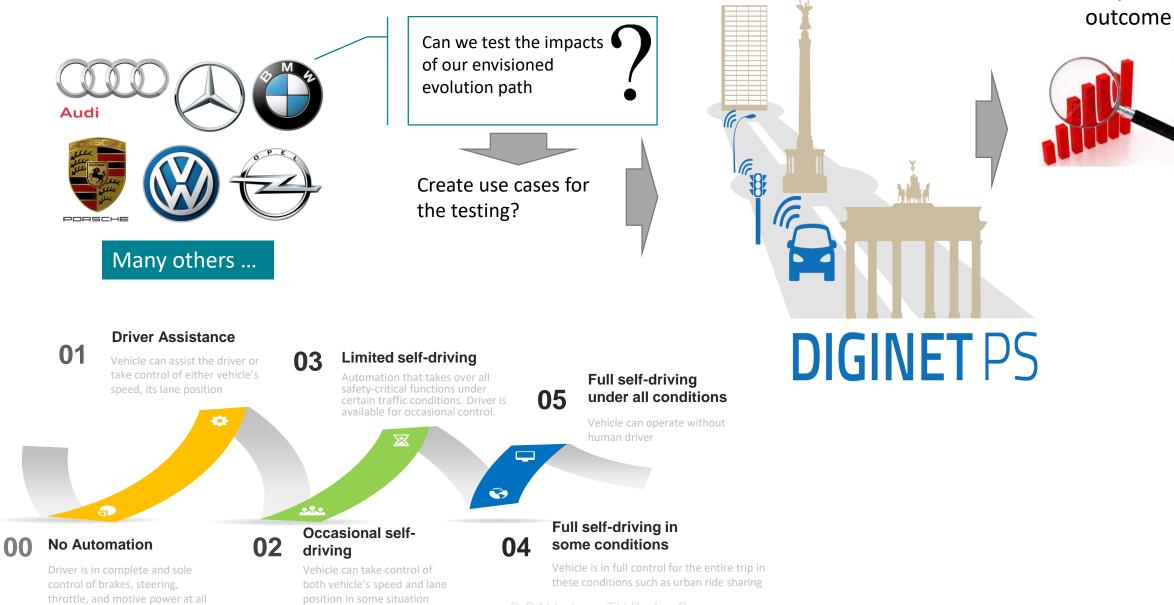








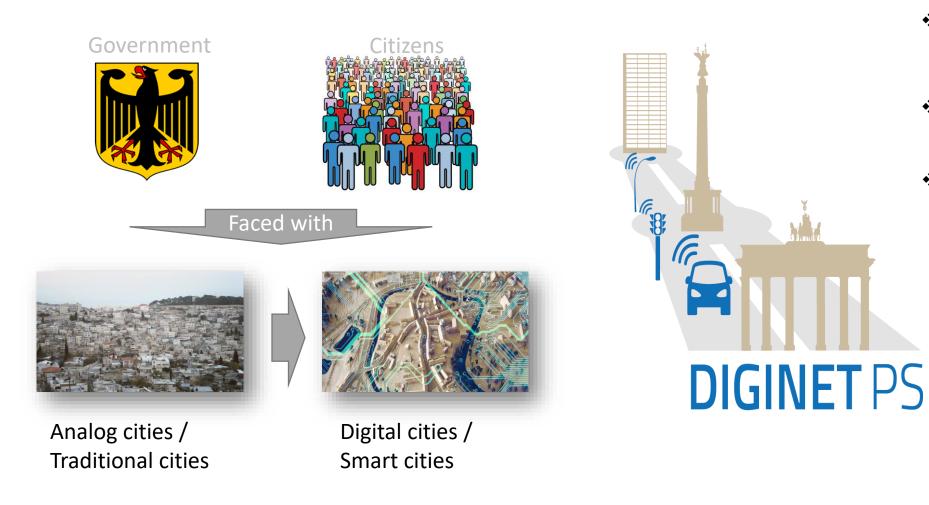
DigiNet-PS Impacts on Vehicle Manufacturers



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Analyze the

DigiNet-PS Impacts on Government and Citizens



- Study the impact of autonomous driving on citizens
- Predict major changes to urban landscape
- Study citizens' perception by realizing various use case scenarios

DigiNet-PS Impacts on entrepreneurs and startups

-







Many others ...

- Ecosystem
 - Business models for future transportation



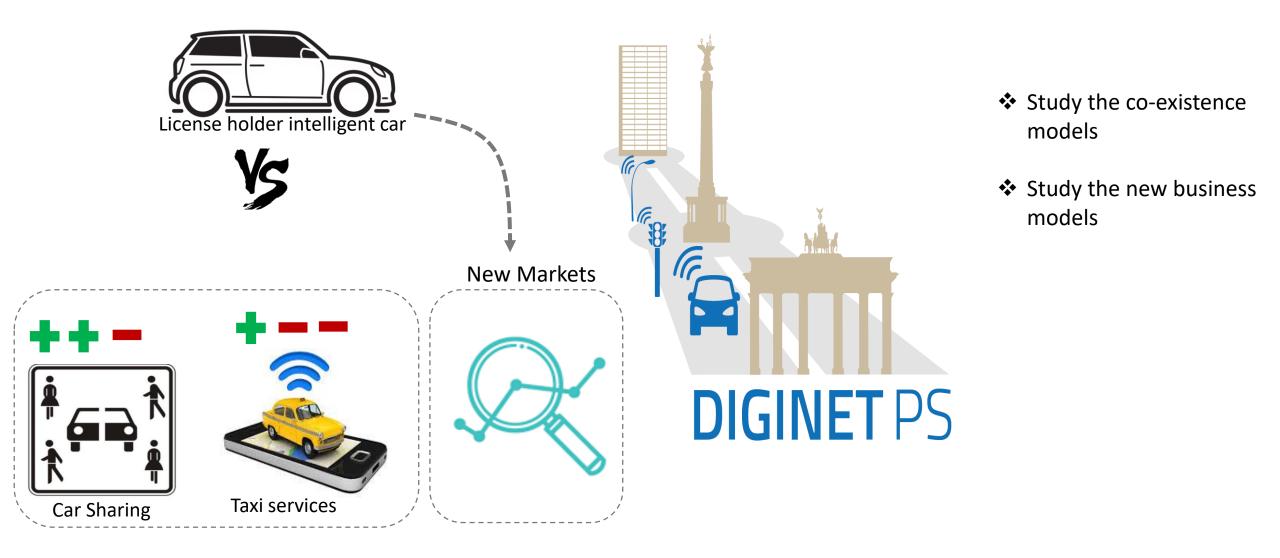
Data

DIGINET PS

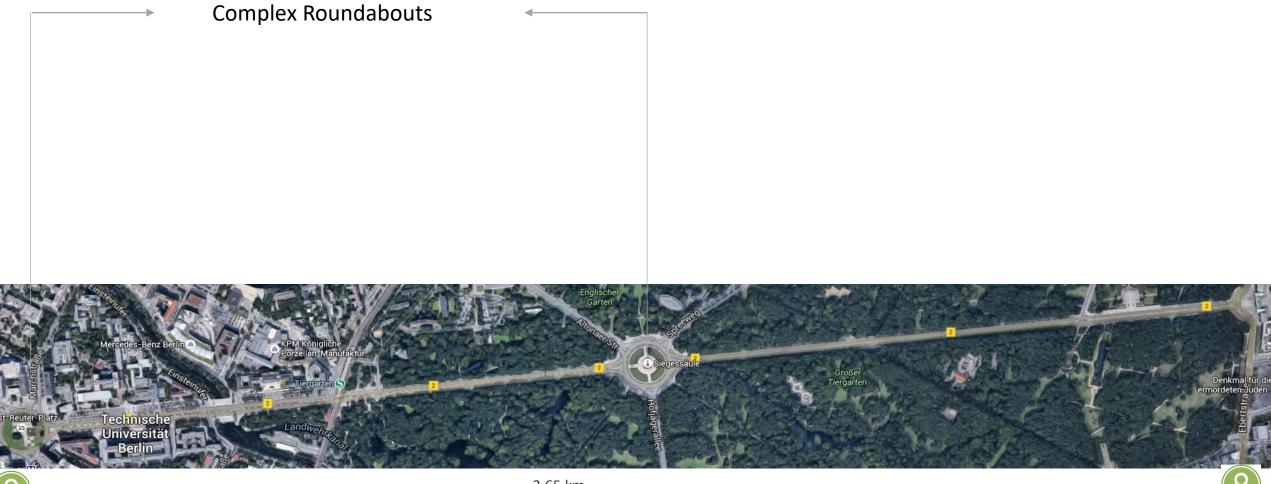
R

- Study and inputs for the business model shifts
- Enable the entrance of new entrants in the market

DigiNet-PS Impacts on existing markets



Driving in a Digitized City DigiNet-PS Route Overview





3,65 km, three-lane each direction, with road markings



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Driving in a Digitized City DigiNet-PS Route Overview

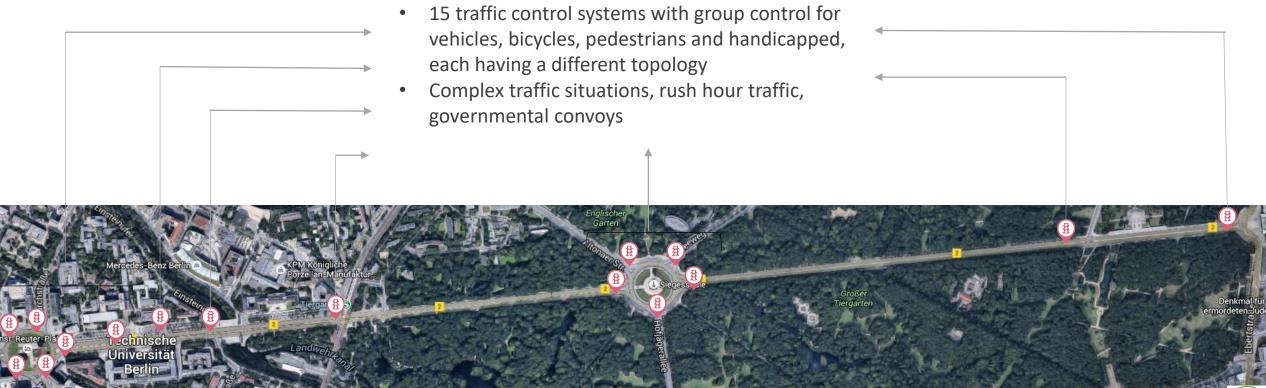
- Complex parking situations,
- marked and non-marked,
- parallel and slanted parking (about 1000 parking spaces),
- center island parking (about 600 parking spaces),
- separate parking areas





3,65 km, three-lane each direction, with road markings Brandenburget To

Driving in a Digitized City DigiNet-PS Route Overview

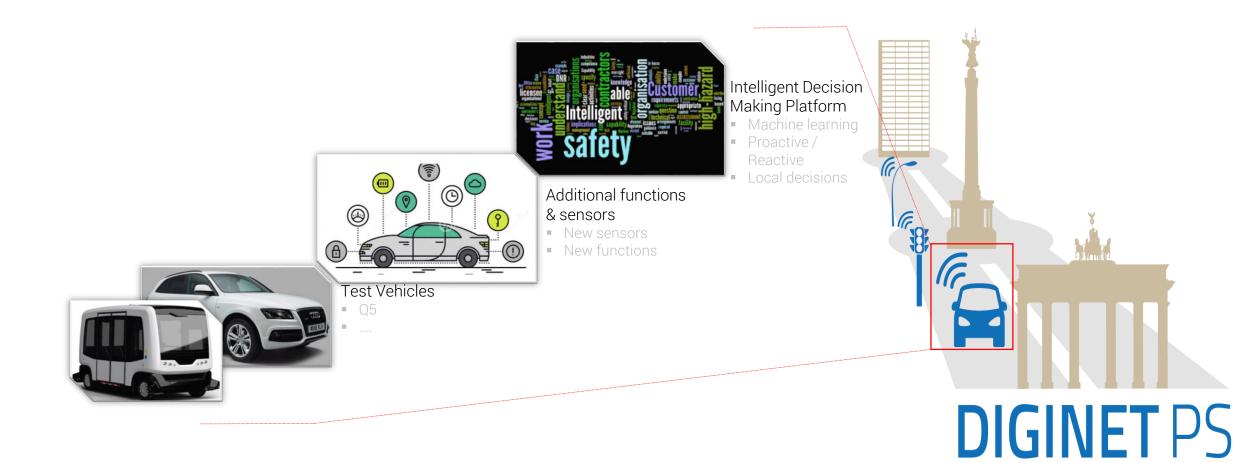




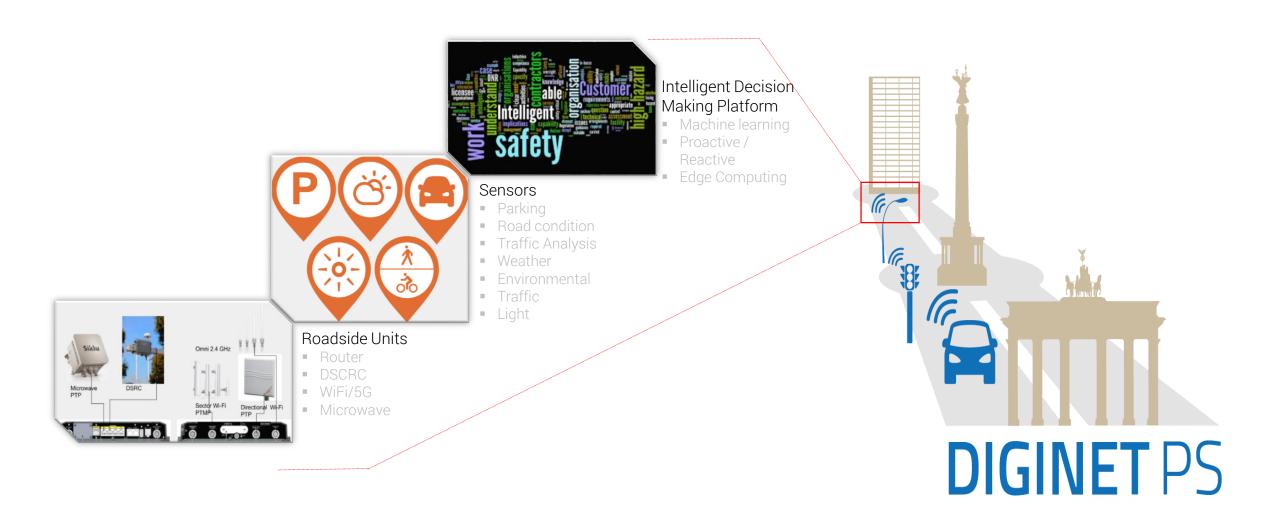
3,65 km, three-lane each direction, with road markings

Brandenburget To

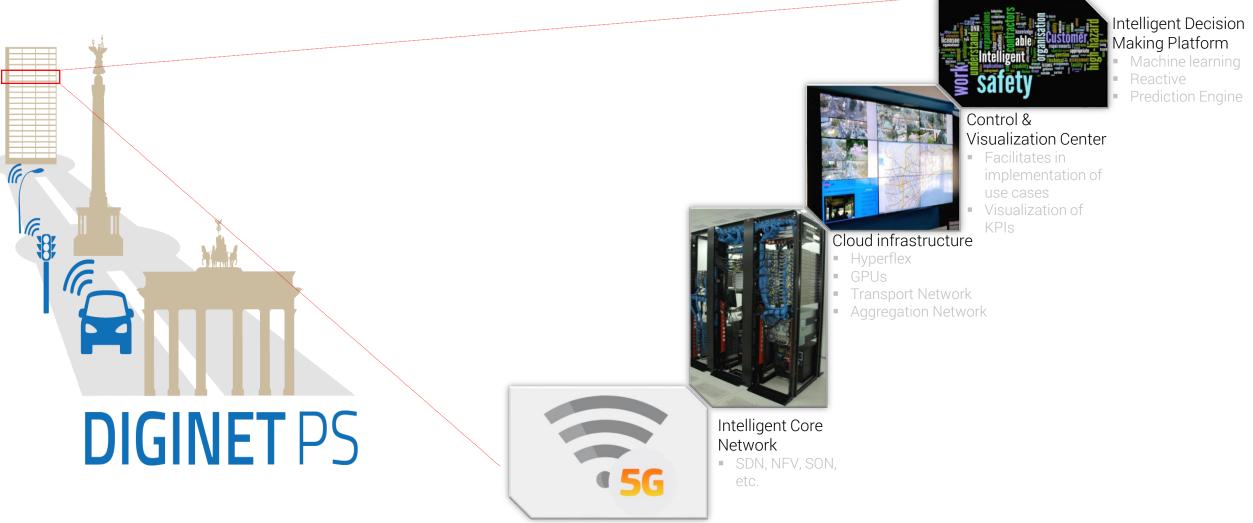
Driving in a Digitized City DigiNet-PS Vehicle Solution Suite



Roadside Unit Solution Suite



DigiNet-PS Cloud Solution Suite



National Schaufenster for Autonomous Driving

DigiNet-PS Decisions Hierarchy

Global View & Control

Local Decision Making Vehicle

DM

data **(**P) Edge computing ✤ Time critical Ġ. decisions Analysis Plan Sense Execute

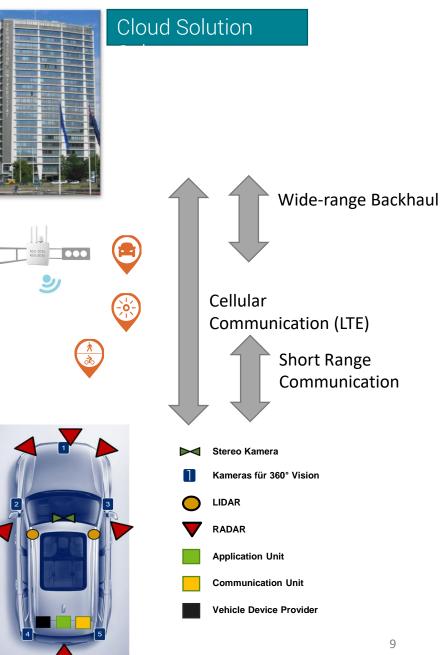
✤ Machine learning

✤ Integrating

Proactive decisions

stakeholders & huge

heterogeneous sensory





R

Roadside Unit

Edge Processing

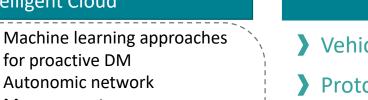
& Decisions

Vehicle

Vehicle

Software Stack

+ new functions



applications

stakeholders

vehicles

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Development APIs for different

Applications & logic for co-

existing with traditional

Use Cases

- Vehicle Testing
- Protocol Road
- Navigator App
- **Uni Shuttle**
- Application Development
- Control Center
- Environmental Friendly Driving

Sustainability

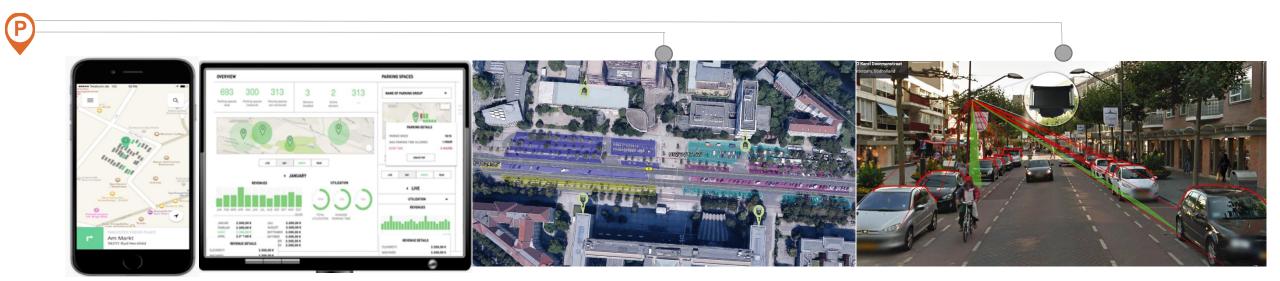
- Reduce fuel consumption and pollution
 - Avoiding search for parking spaces
 - Avoiding congested routes
 - Avoiding stop & go by choosing suitable

✤ Safety

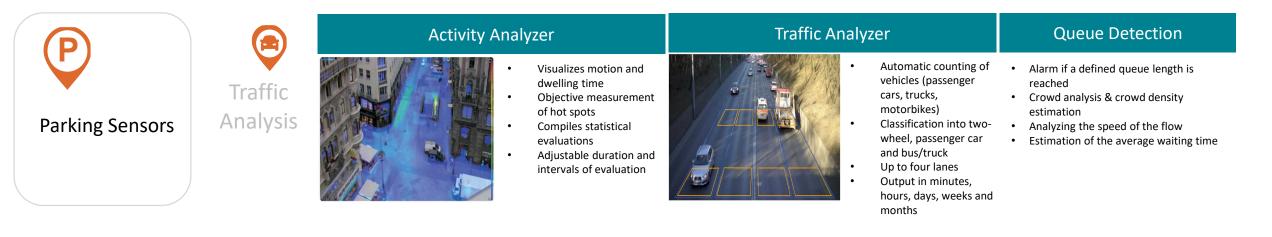
Reduce accidents

* Efficiency

Reduced travel time

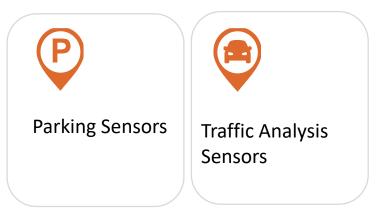












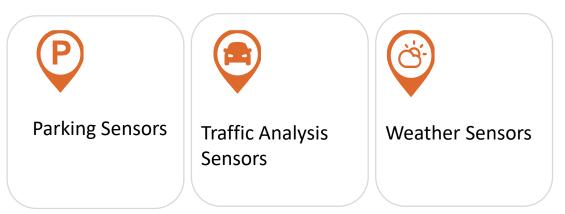






- Temperature,
- Relative humidity,
- Precipitation intensity,
- Precipitation type,
- Precipitation quantity,
- Air pressure,
- Wind direction,
- Wind speed







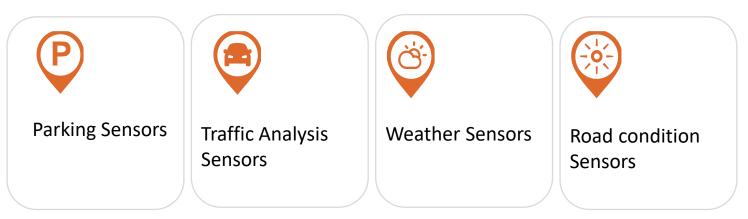




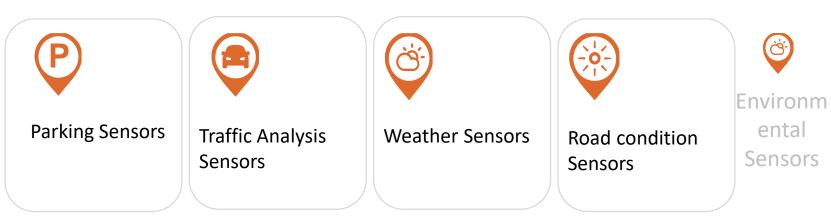
- Layer thickness of water, snow and ice,
- Surface conditions (dry, damp, wet, snow, ice),
- Friction,
- Road surface temperature















- 03,
- PM1,
- PM2.5,
- PM10



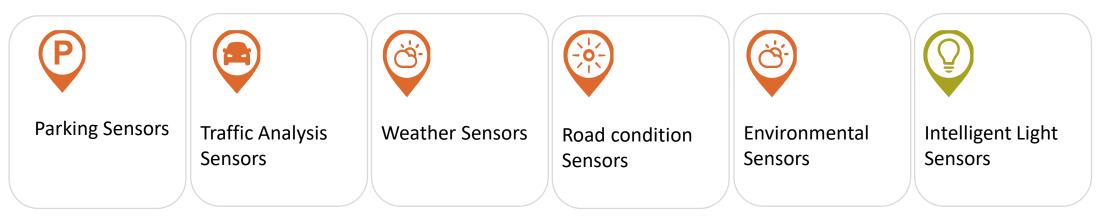




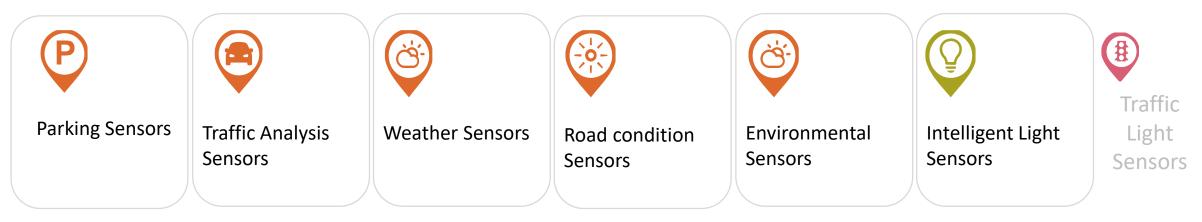






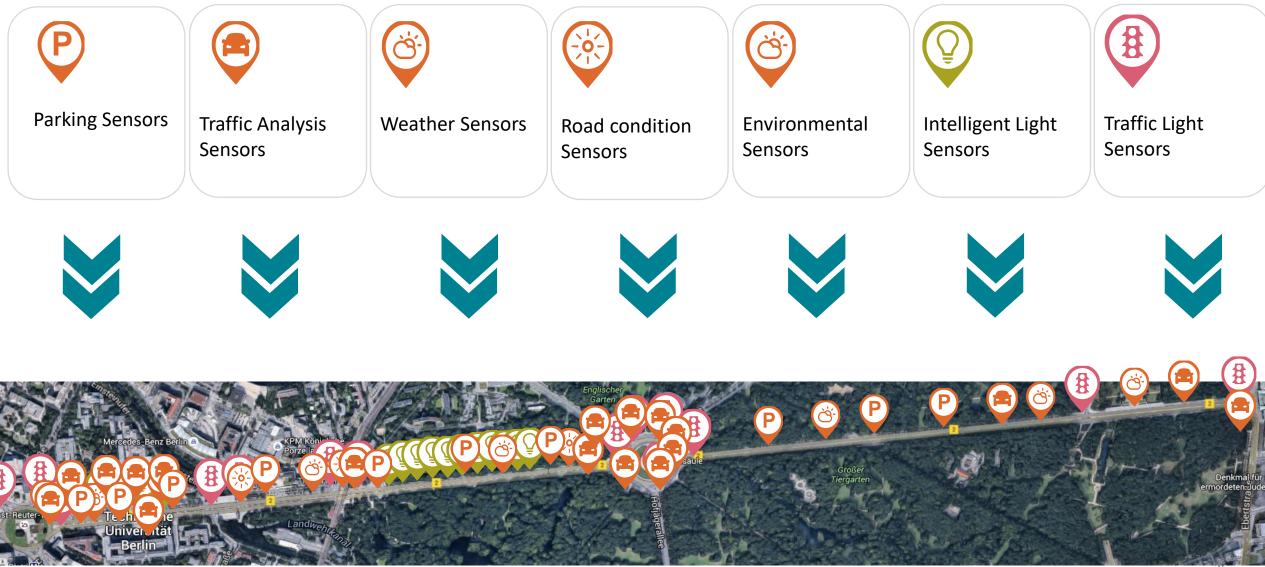


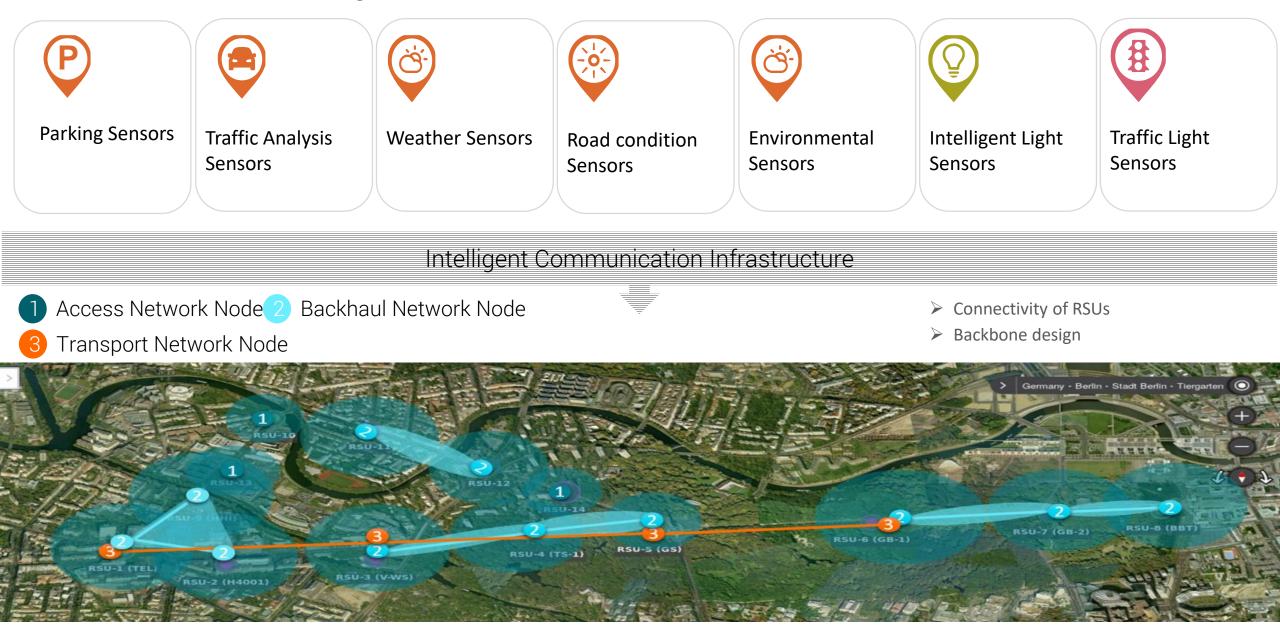






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Unique Standpoint of DigiNet-PS



Intelligent Vehicle with human driver like perception

Business Opportunities

New Eco-systems &



Digital Urban Environment

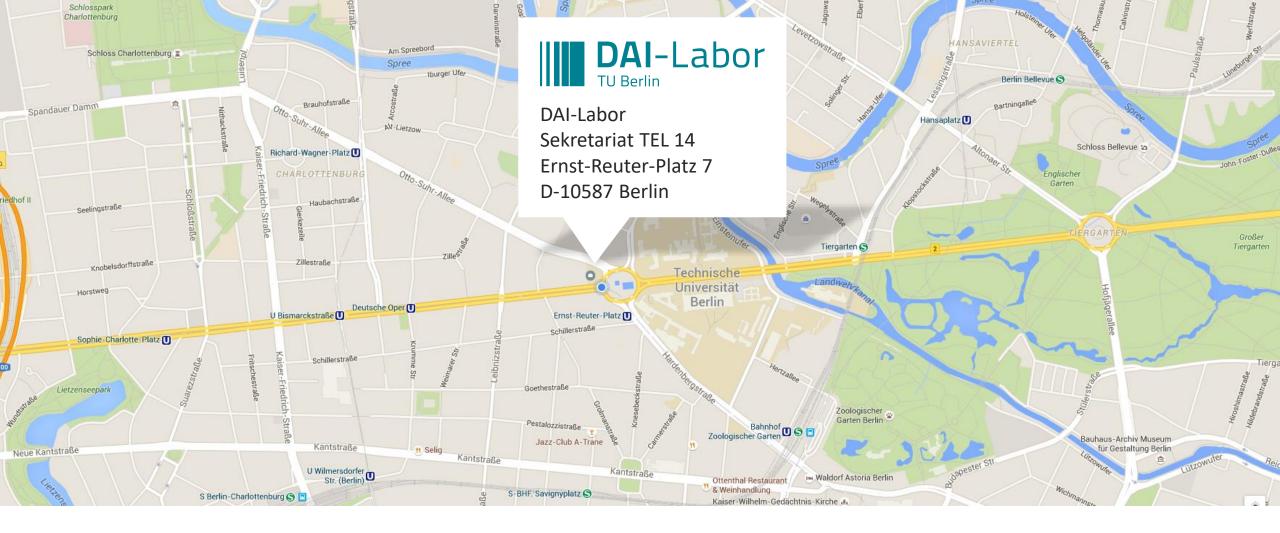


Improved Quality of Life

Project Consortium



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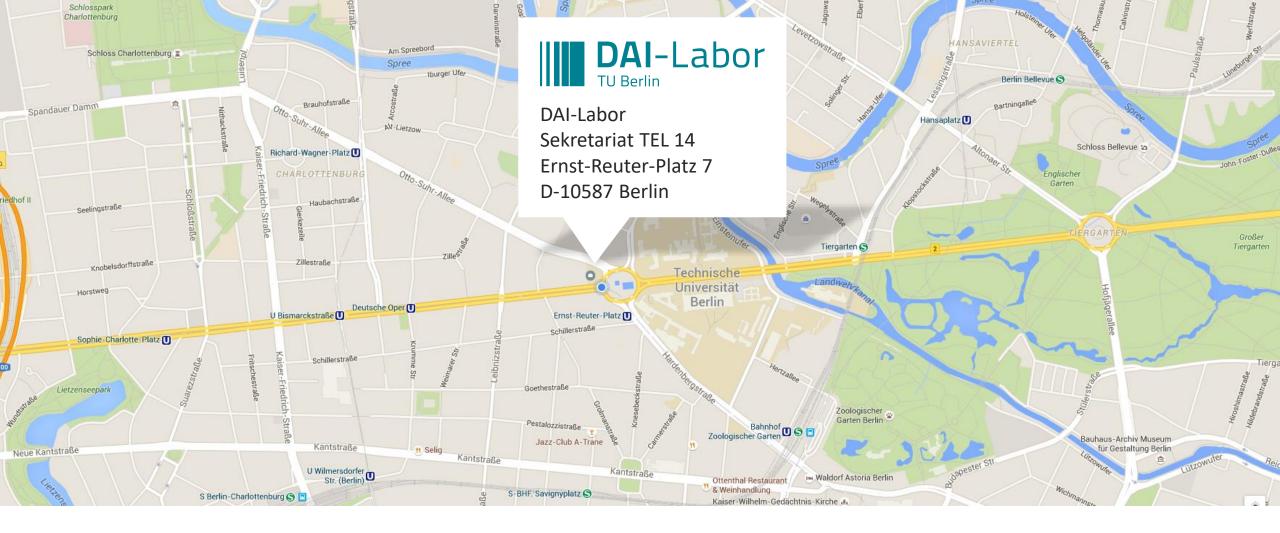


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