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Challenges to Vehicle E/E Architectures

Increasing functionality poses a challenge to vehicle E/E architectures:

Full performance without malfunction

Differentiating features (,Vehicle-DNA')

Cost-optimum solution for HW and R&D

One approach covering all models within a platform

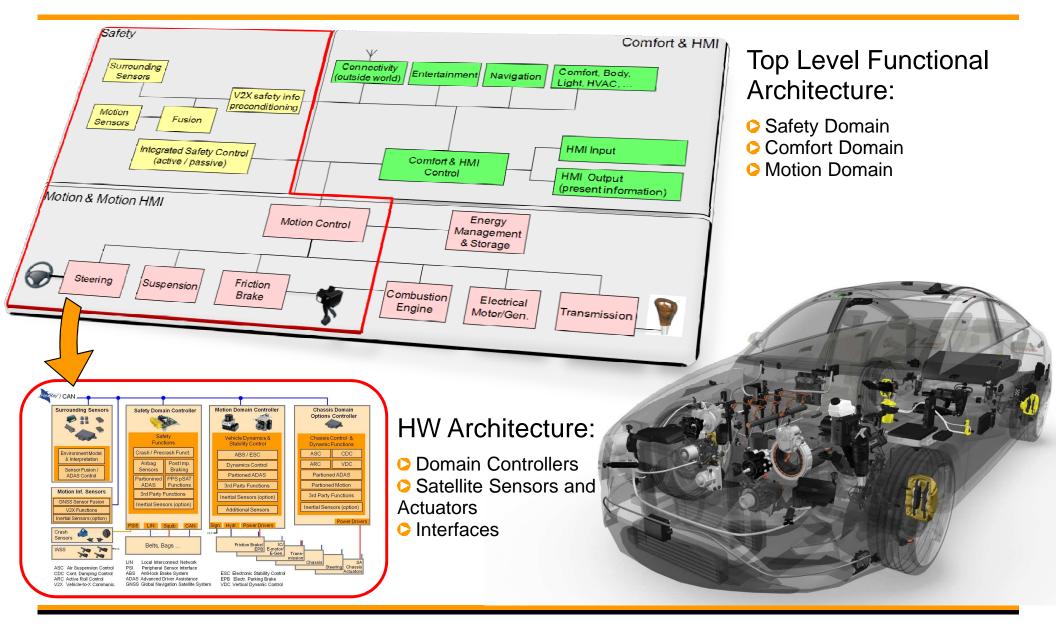
Fullfillment of functional safety requirements

Therefore vehicle E/E architectures have to be developed featuring

- modular & scalable HW & SW
 - Functional vehicle identity via specific function modules
 - Standardized modules for non-differentiating functions, e.g. basic SW
- clear & standardized interfaces
- a structured functional decomposition based on already intensively networked functional areas (domains)

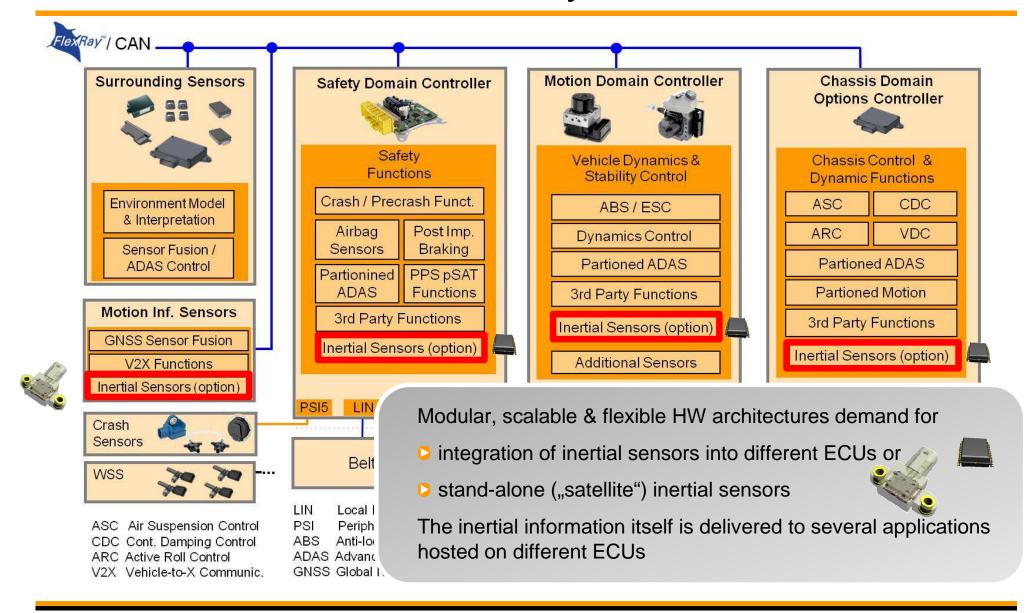


From Functional to HW Architecture



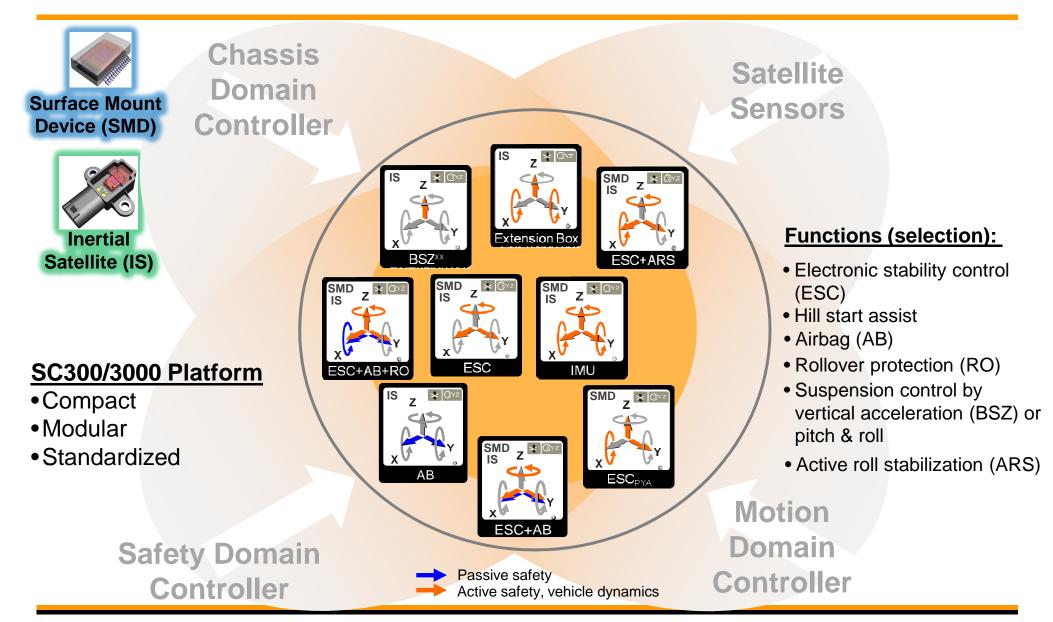


Vehicle HW Architecture of the Safety and Motion Domains



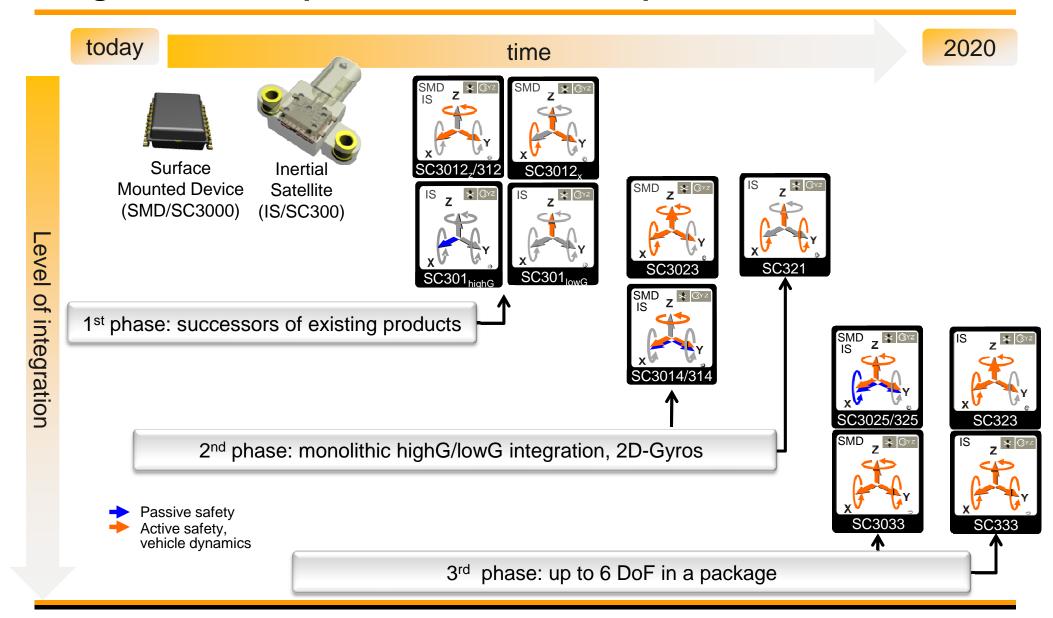


Product – Function Matrix



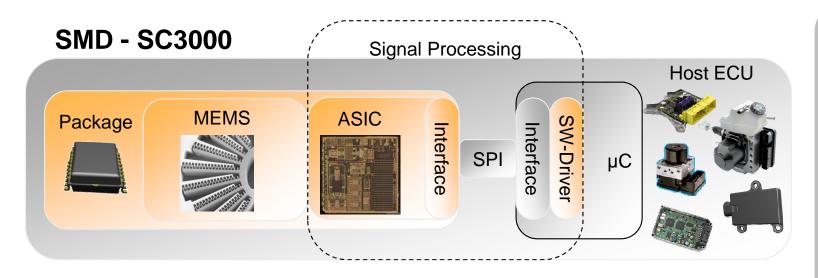


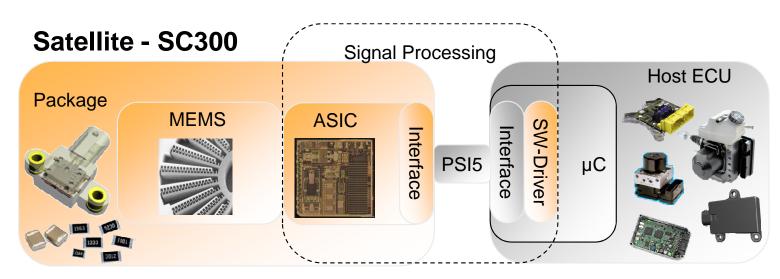
Long-Term Development Phases/Roadmap





Product & System Architecture





SC300/3000 Architecture Advantages:

- Create synergies across considered products for all sub-components
- Find best-cost & flexible packaging technology for SMD and satellite devices
- Use costreduction capabilities of SWsensor driver approach (SESI)

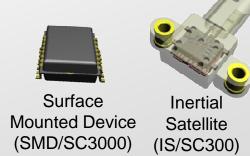


Platform Solution

Platform for Best-Cost Inertial Sensor Systems

Modular & scalable product platform for inertial sensors with a software interface to function algorithms

- Modular concepts for ASIC, SW, MEMS & packaging for a platform of 14 products
- Decision for the most promising cost-efficient platform:
 - Packaging: Leadframe- or PCB based
 - Interface: SPI for SMDs, PSI5 for satellites
 - ASIC: modular ASIC approach; no int./ext. µC in sensor HW
 - > SW: no SW in sensor HW; modular sensor driver architecture on host-ECU
 - MEMS: set of basic MEMS elements for complete product portfolio







All Sensing Systems on for More Safety

