

# Increased Consumption in Oversaturated City Traffic Based on Empirical Vehicle Data

Gefördert durch:



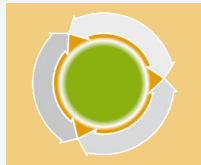
Bundesministerium  
für Wirtschaft  
und Energie

aufgrund eines Beschlusses  
des Deutschen Bundestages

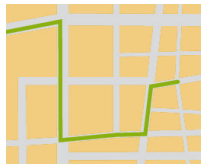
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### Cooperative Infrastructure



### Regional Network

- Optimal energy use by adaptive route guidance

Strategic Routing  
> 5km



### Urban Road

- Electronic horizon energy- and traffic optimised driving, avoiding stops at traffic lights

Adaptive driving  
< 5km



### Smart Intersection

- energy- and traffic optimised stopping, waiting and deciding at traffic light

Tactical driving  
< 1km

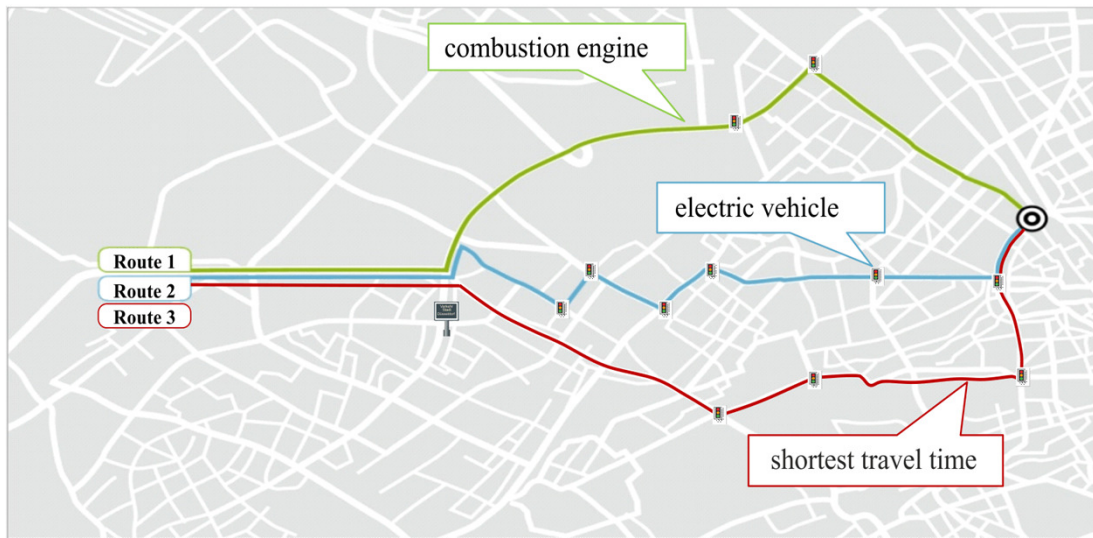
## Regional Network

### Goal:

Show energy efficient navigation based on precise traffic and infrastructure information

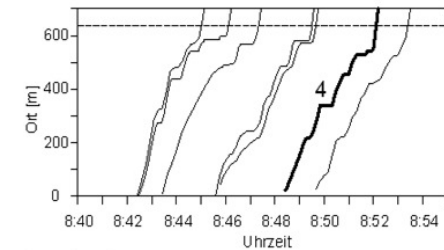
### Basis:

- Precise traffic data
- Engine adaptive consumption simulation
- Analysis of traffic breakdown at network nodes
- Traffic control with minimized breakdown probability
- Urban traffic management

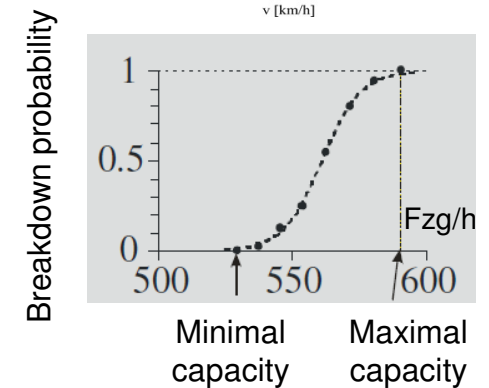
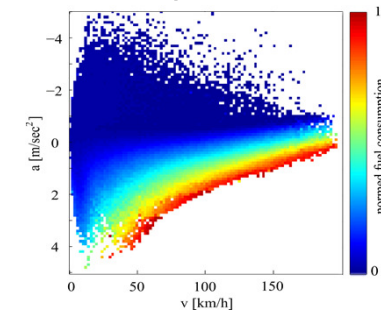


### Precise data with mobile devices

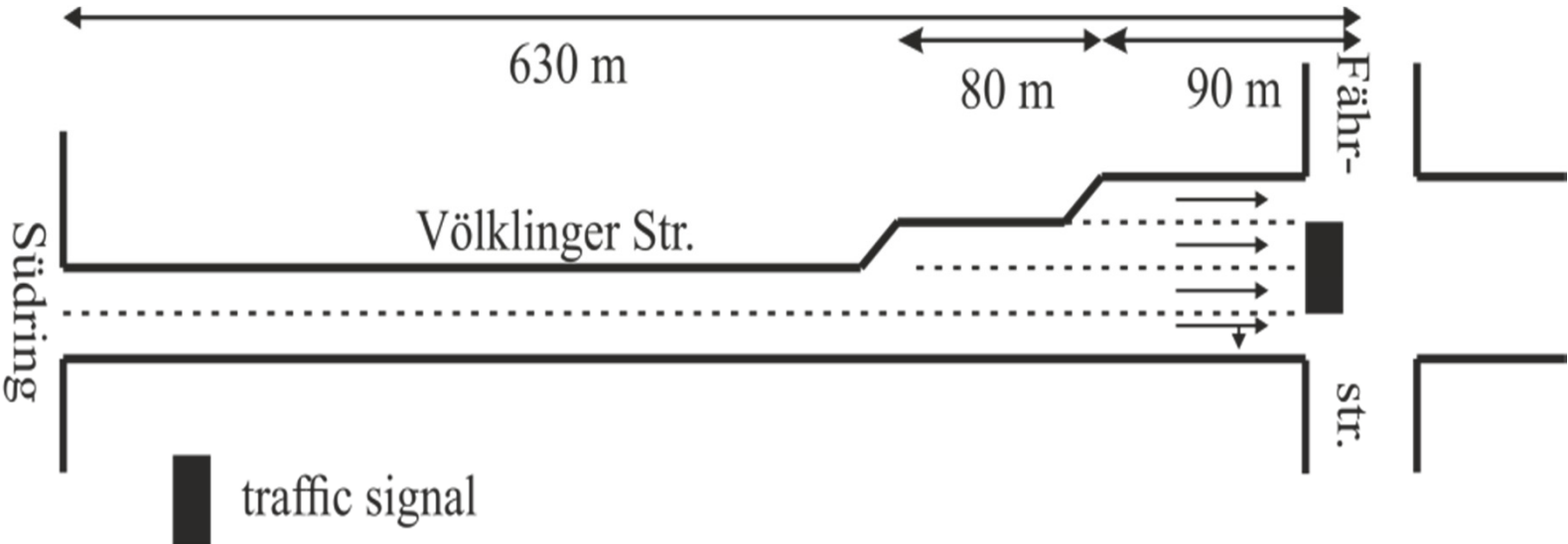
Völklinger Straße, 09.11.2011



### Consumption matrix



Road section of "Völklinger Straße" in Düsseldorf. The speed limit is 60 km/h.

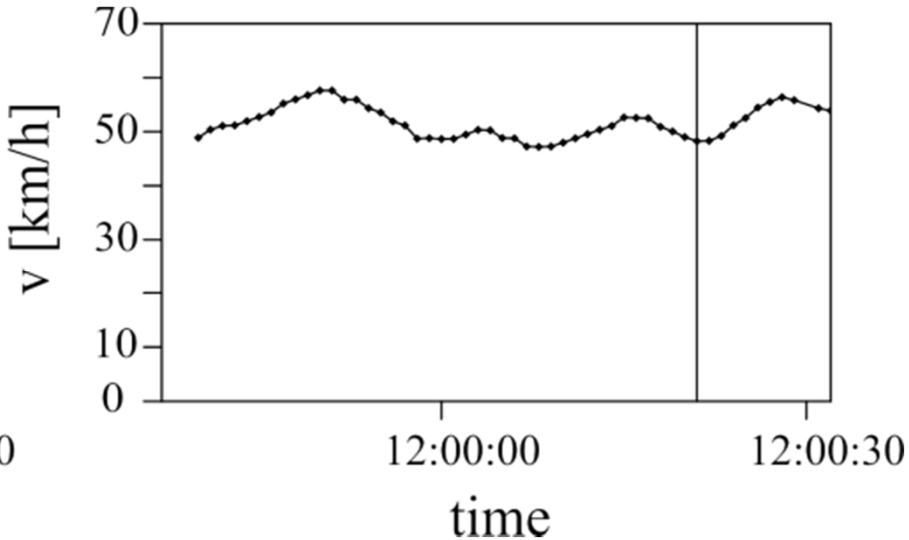
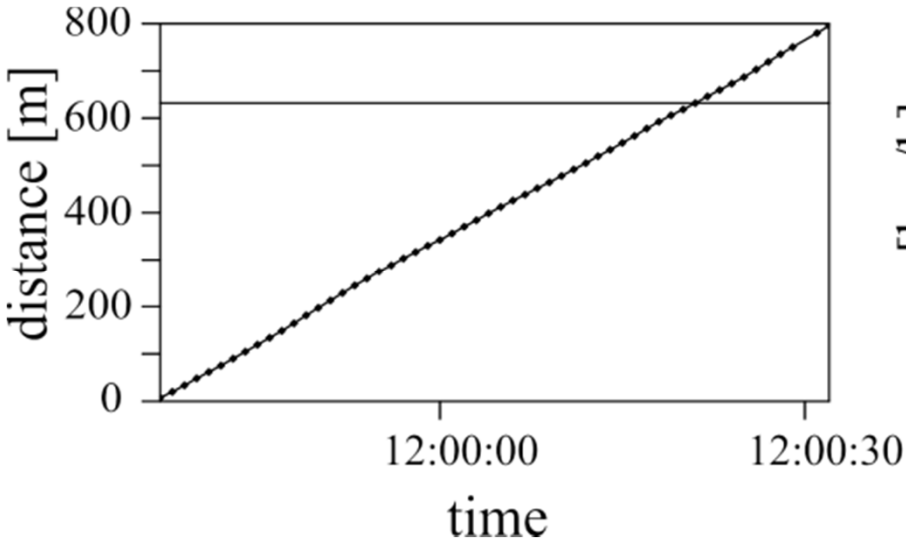


## Overview of the 15 vehicle trajectory classes

<i>Class</i>	<i>Average Speed [km/h]</i>		<i>Number of Stops</i>	
	<i>Minimum</i>	<i>Maximum</i>	<i>Minimum</i>	<i>Maximum</i>
<i>1</i>	30	75	0	0
<i>2</i>	30	75	1	1
<i>3</i>	15	30	0	1
<i>4</i>	15	30	2	4
<i>5</i>	10	15	0	1
<i>6</i>	10	15	2	4
<i>7</i>	10	15	5	6
<i>8</i>	8	10	5	6
<i>9</i>	8	10	7	10
<i>10</i>	6	8	5	6
<i>11</i>	6	8	7	10
<i>12</i>	6	8	11	13
<i>13</i>	3.5	6	7	10
<i>14</i>	3.5	6	11	13
<i>15</i>	0	3.5	13	30

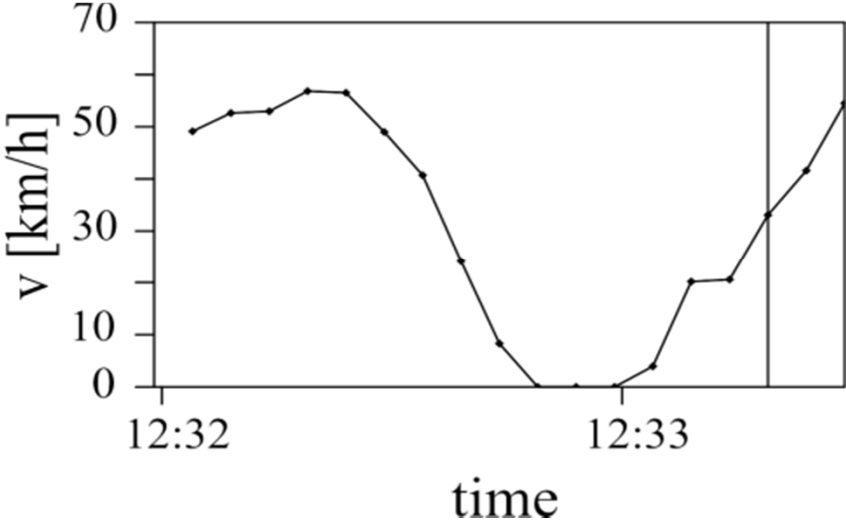
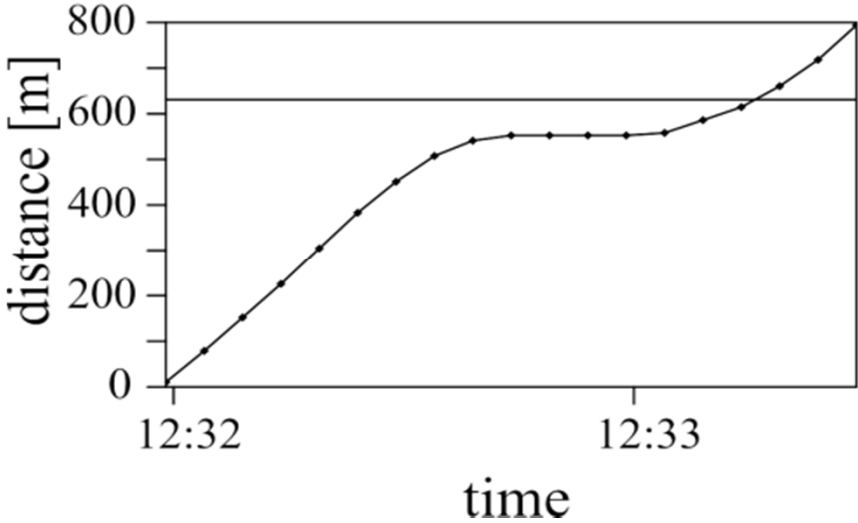
**Definition of „stop“:** speed lower than 5 km/h and a second stop can occur only 10seconds after the first one.

Representative of class 1 (undersaturated traffic, no stop);  
vehicle trajectory and speed profile from February 2013



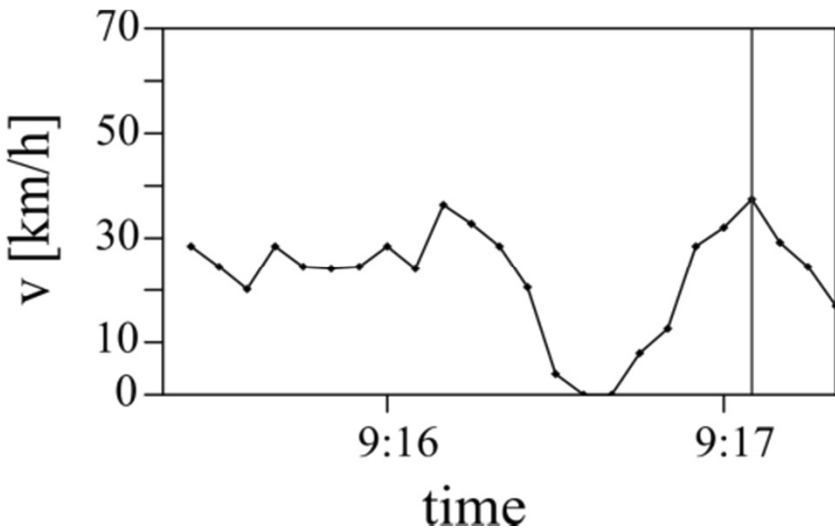
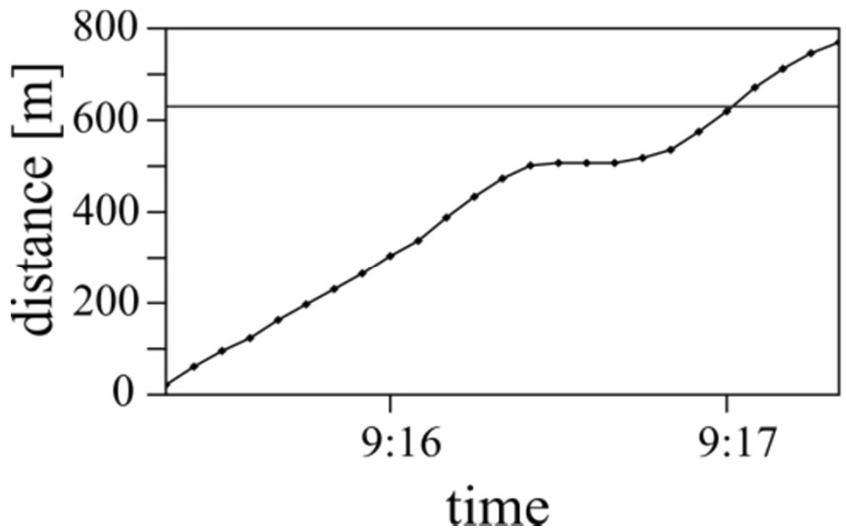
Free flow

Representative of class 2 (undersaturated traffic, one stop);  
vehicle trajectory and speed profile from November 2011



One stop at light signal

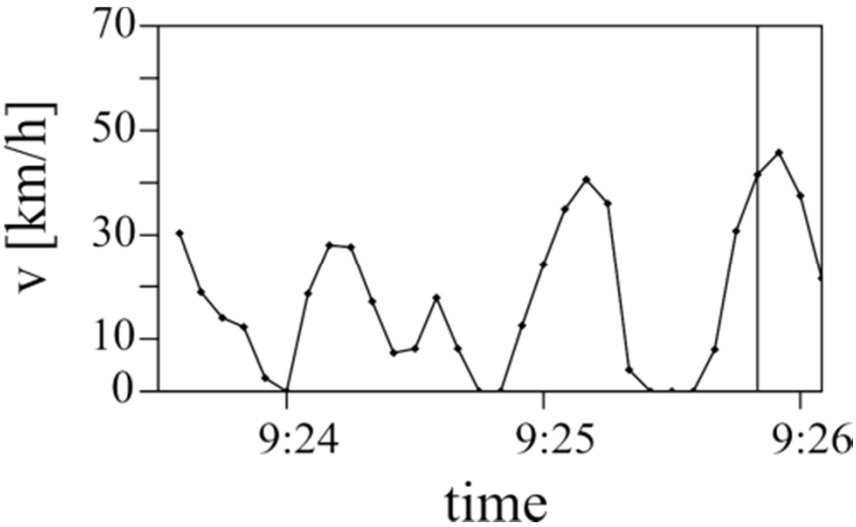
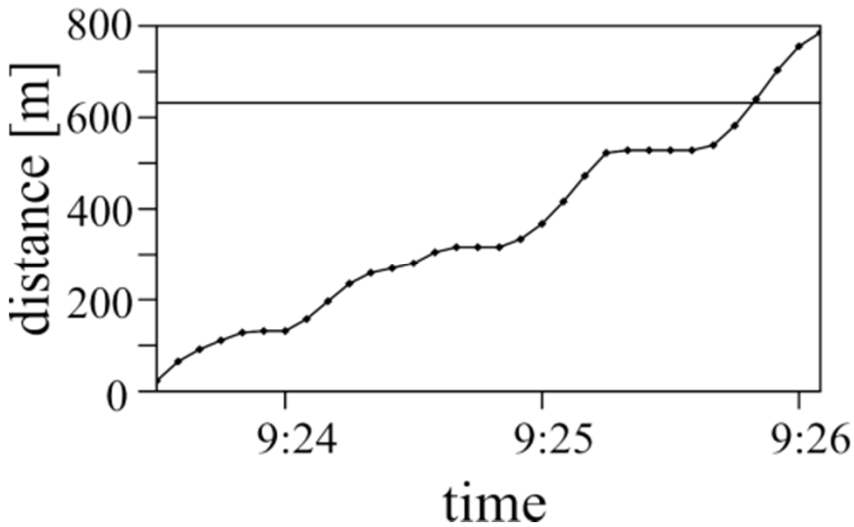
Representative of class 3; vehicle trajectory and speed profile from February 2013



One stop at light signal and lower speed (“synchronized traffic flow”): oversaturation („congested“)

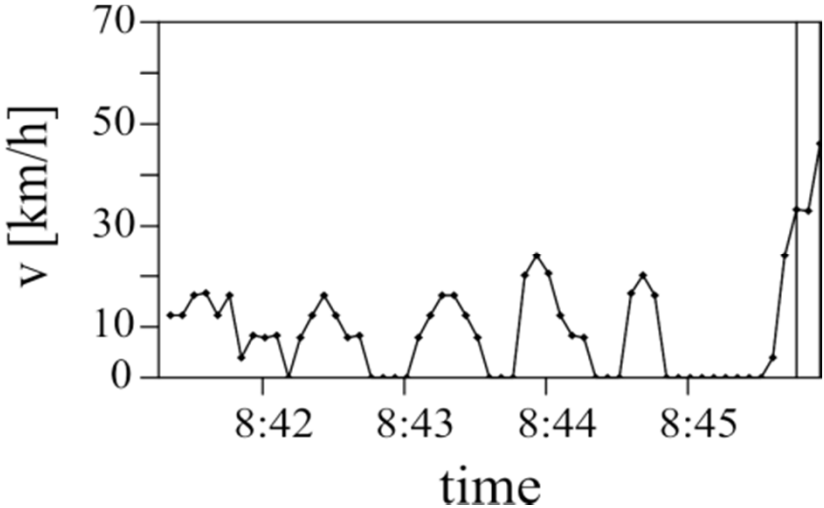
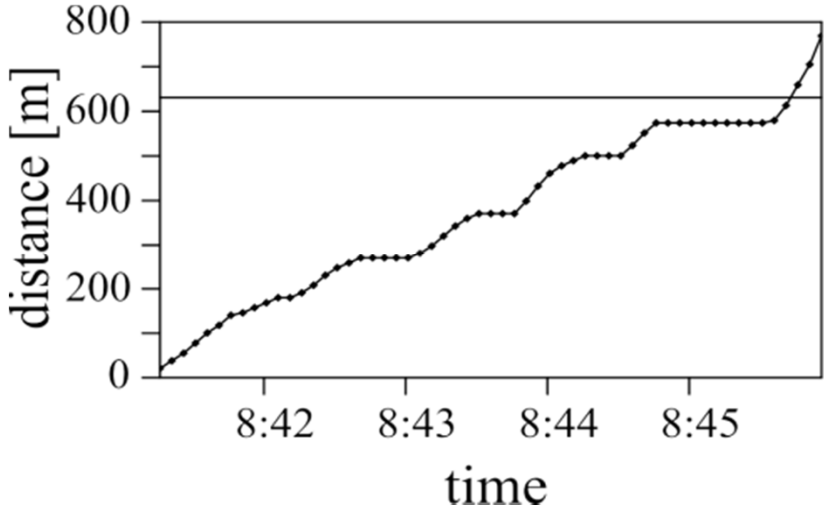


# Representative of class 4; vehicle trajectory and speed profile from February 2013



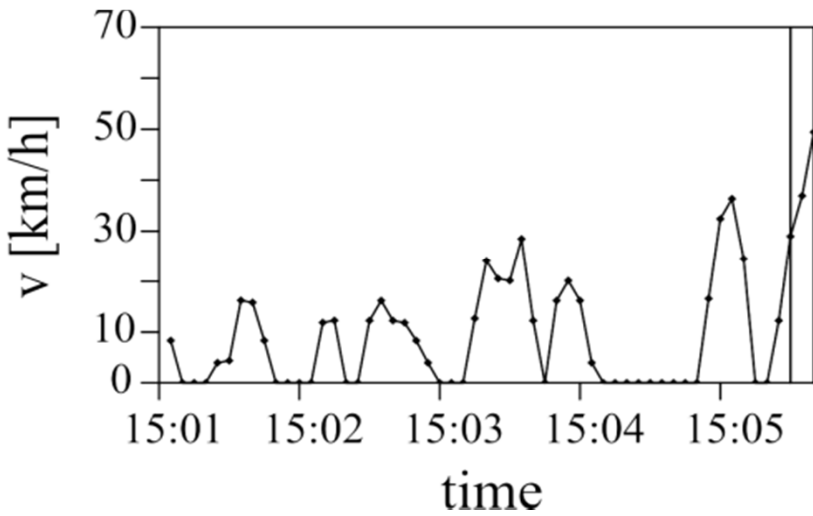
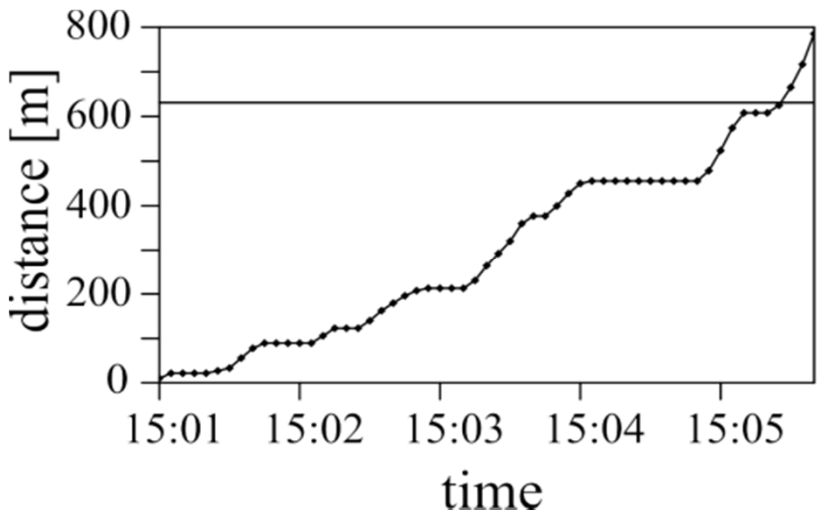
Three stops and lower speed: oversaturation („congested“)

# Representative of class 8; vehicle trajectory and speed profile from November 2011



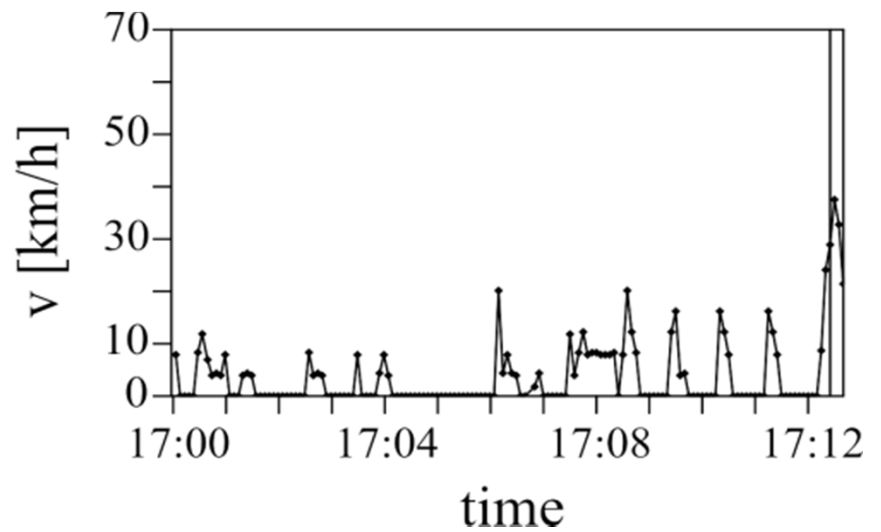
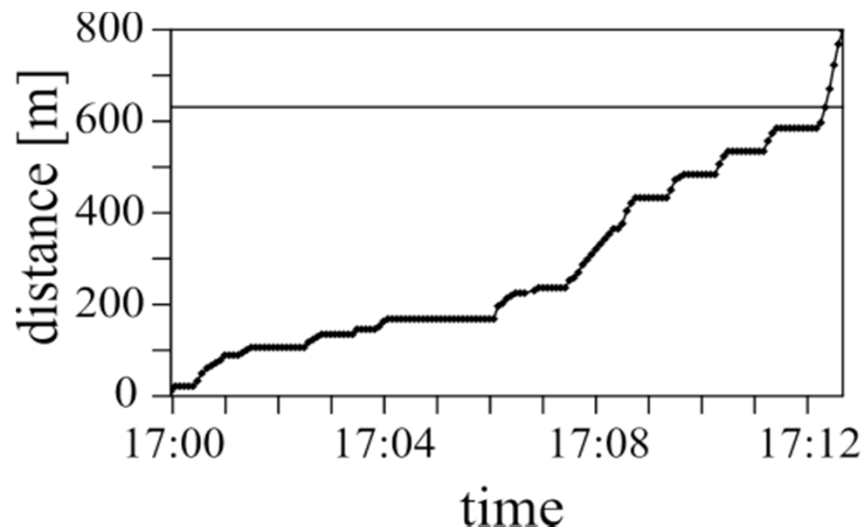
Five stops and lower speed: oversaturation („congested“)

# Representative of class 9; vehicle trajectory and speed profile from February 2013



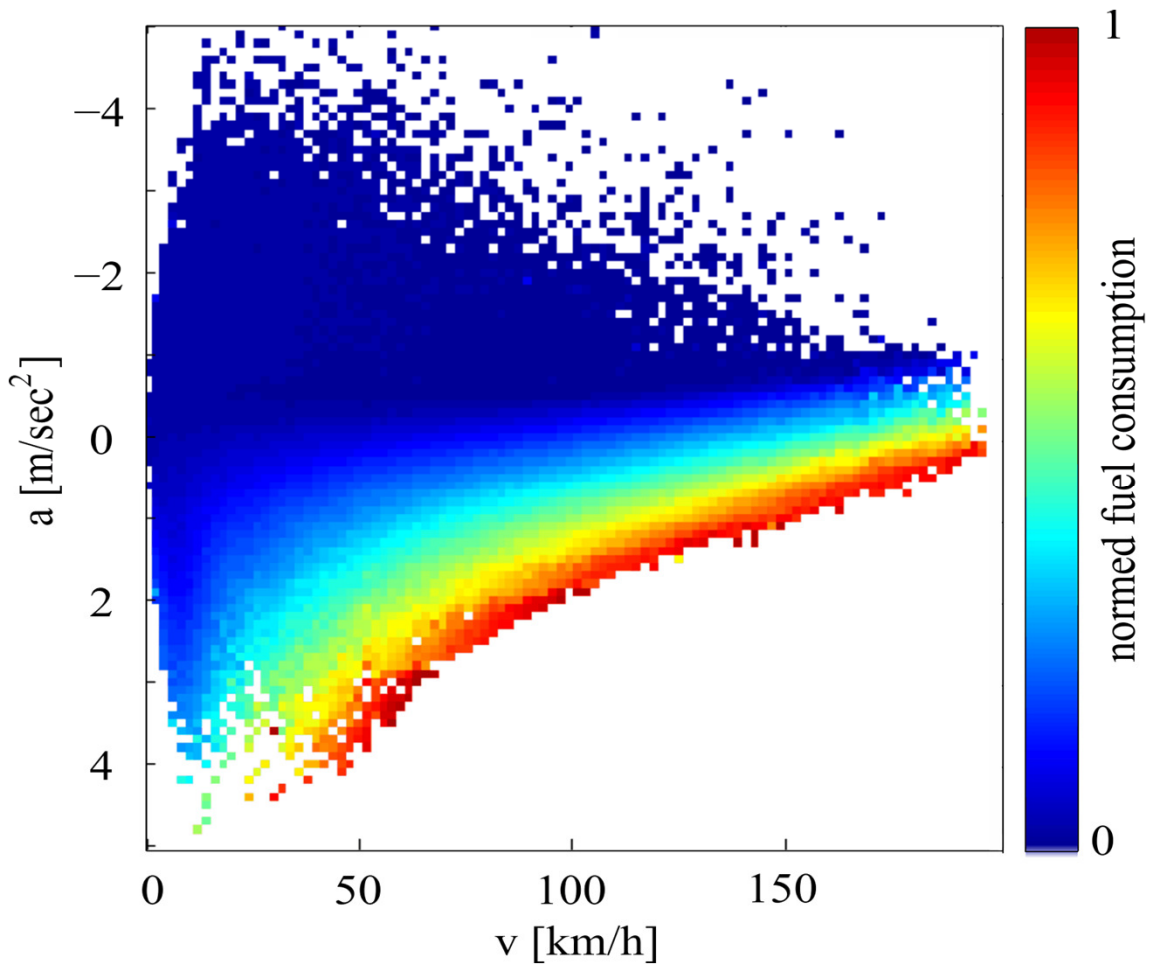
Seven stops and lower speed: oversaturation („congested“)

# Representative of class 15; vehicle trajectory and speed profile from February 2013

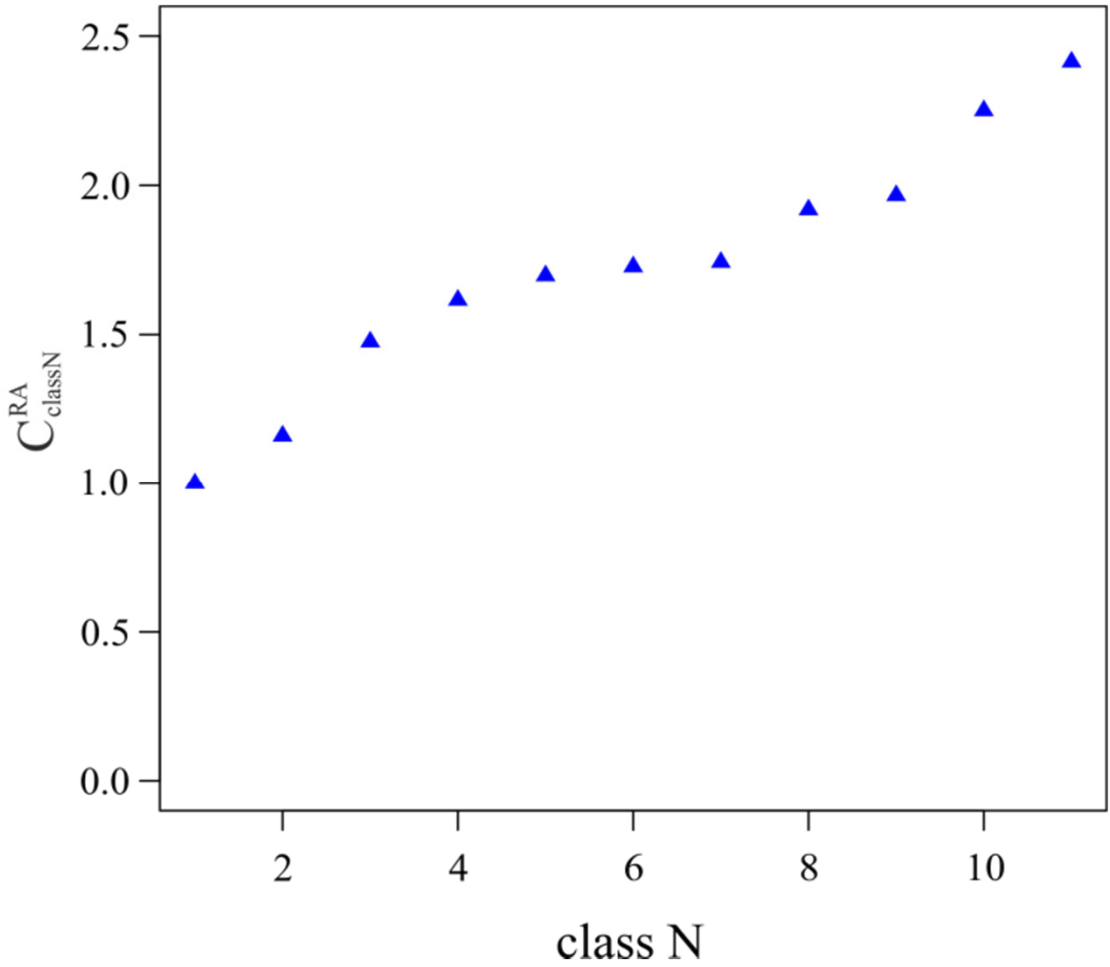


Thirteen stops and very low speed:  
oversaturation („congested“)

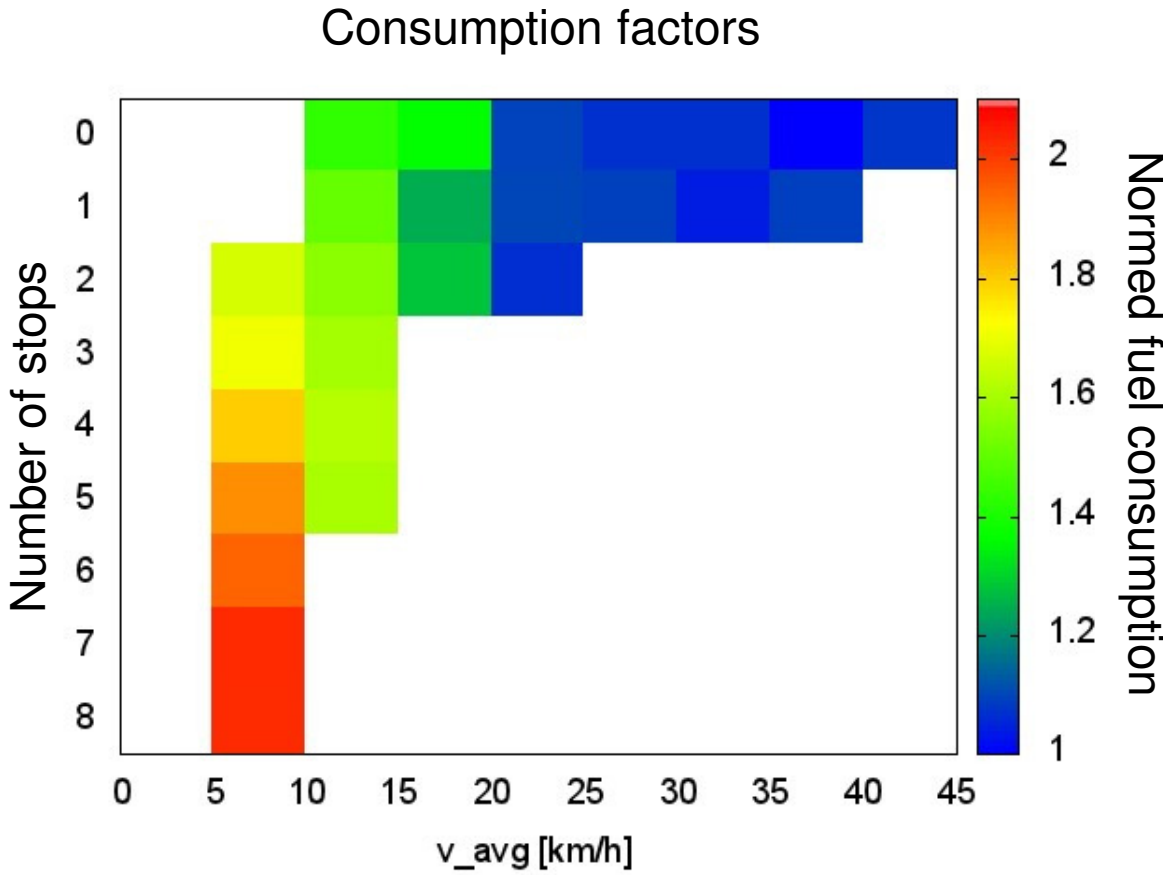
Visualization of an empirical consumption matrix with the parameters acceleration  $a$  and velocity  $v$



# Average fuel consumption for the first 11 traffic pattern classes as a multiple of the average fuel consumption of class 1



$$C_{classN}^{RA} = \frac{C_{classN}}{C_{class1}}$$



Factors for additional fuel consumption based on average speed and number of stops: routing factor in energy efficient navigation

## Conclusions

- Urban congestion situations have been classified with attributes „average speed“ and „number of stops“
- Recorded empirical consumption matrix shows additional fuel consumption as function of vehicle speed and acceleration
- Due to congested traffic in urban regions the additional fuel consumption could be twice as high as in free flow
- Consumption matrices for hybrid/electric vehicles will be developed next