



Safe and Efficient Electrical Vehicle

Simplified Architecture by the use of Decision Units

AMAA 2012 in Berlin

31.5.2012

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Agenda

Simplified Architecture by the use of Decision Units



- » A few words about the project eFuture
- » The idea of a simplified and scalable functional architecture
- » The concept of the Decision Units
- » Vehicle integration



Outline of eFuture

„Safe and Efficient Electrical Vehicle“

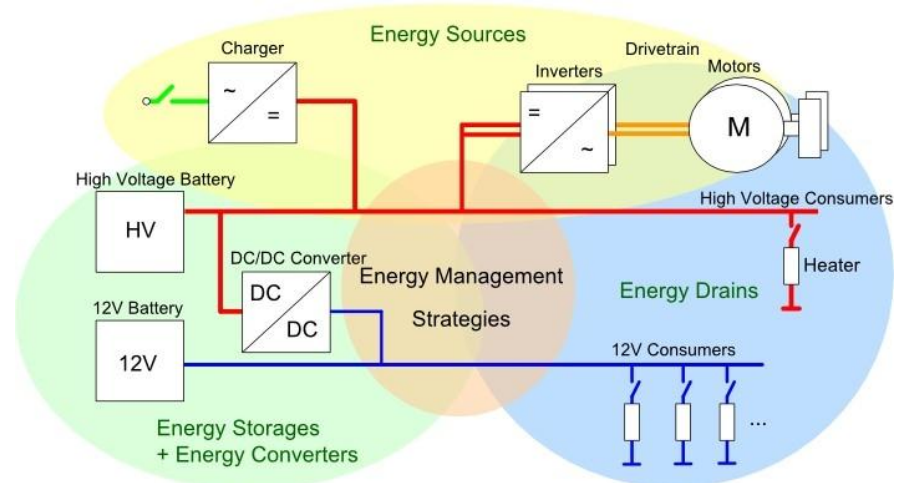
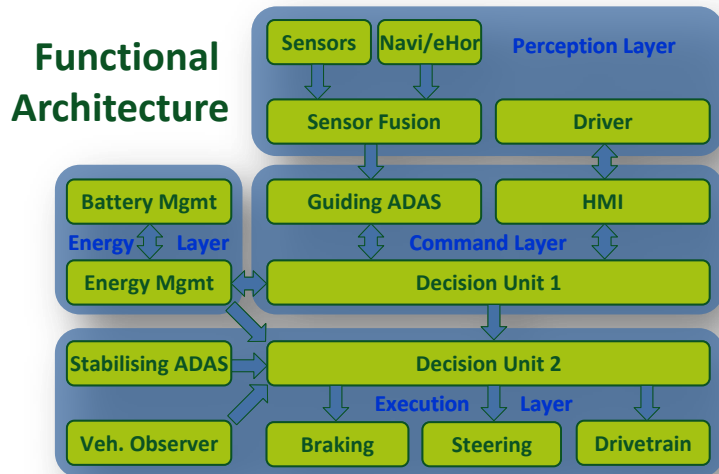


- » Funded by the European Commission (grant no. 258133)
- » Duration 3 years (until September 2013)
- » Budget ca. 7 Mio. Euro
- » Funding ca. 4 Mio. Euro
- » 6 partners from 4 countries
4 from industry
2 research institutes
- » Coordinator:
Intedis, Würzburg

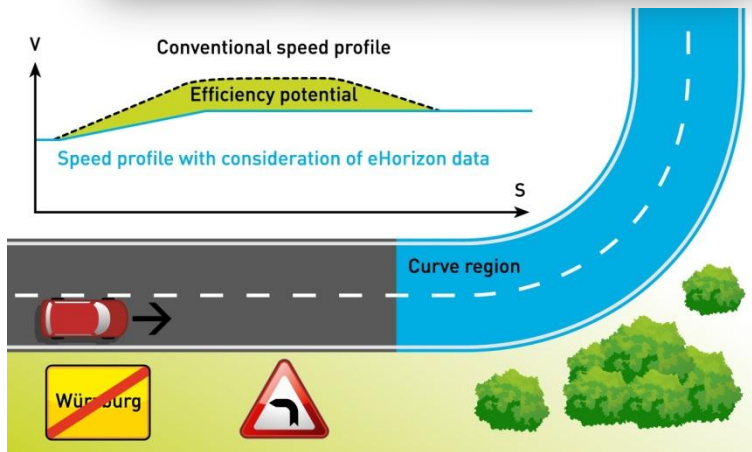


Project focus

„Safe and Efficient Electrical Vehicle“



Energy management



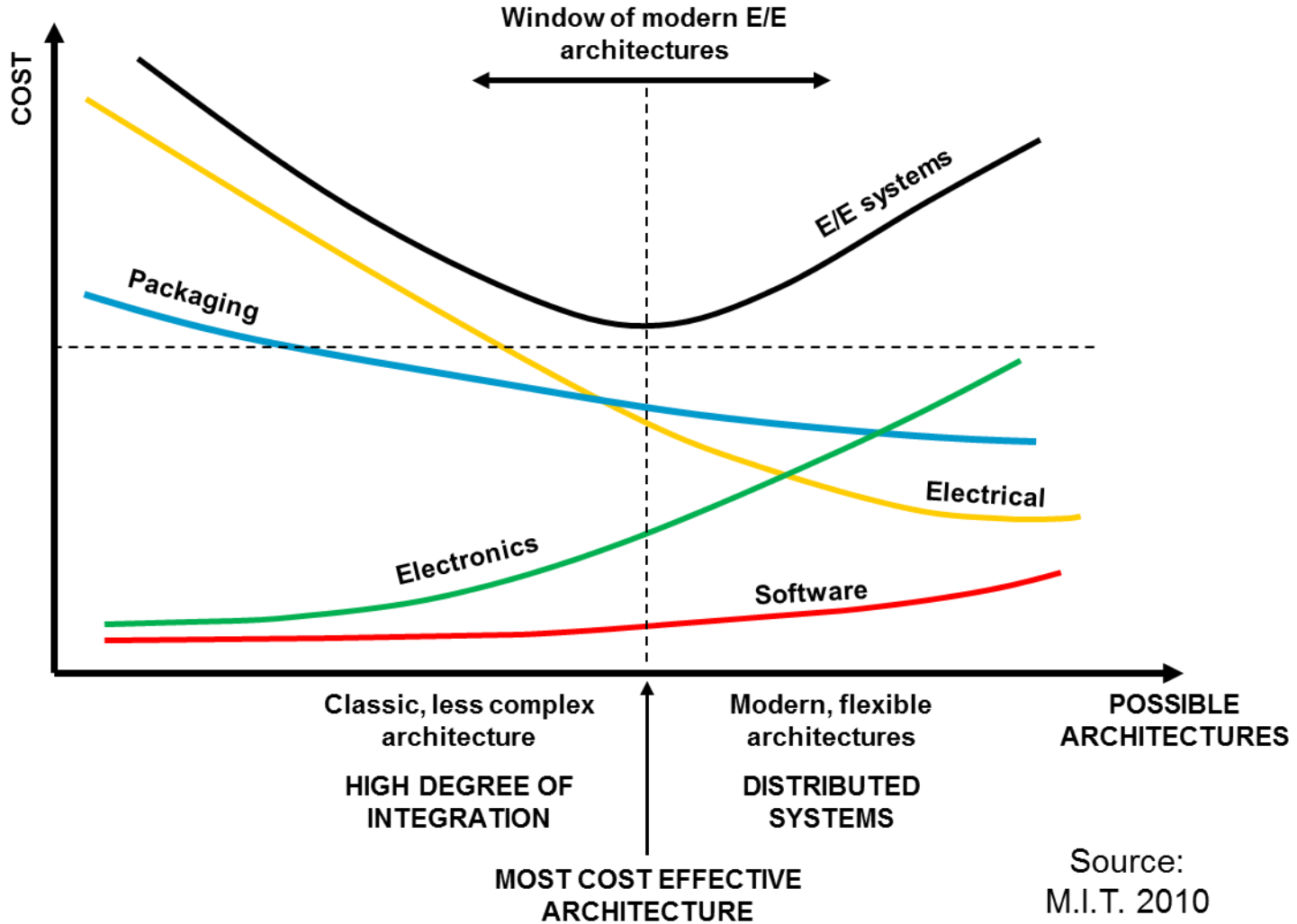
Green Assistance Systems



Driver Coaching

Factors for architecture selection

Flexibility means high software effort

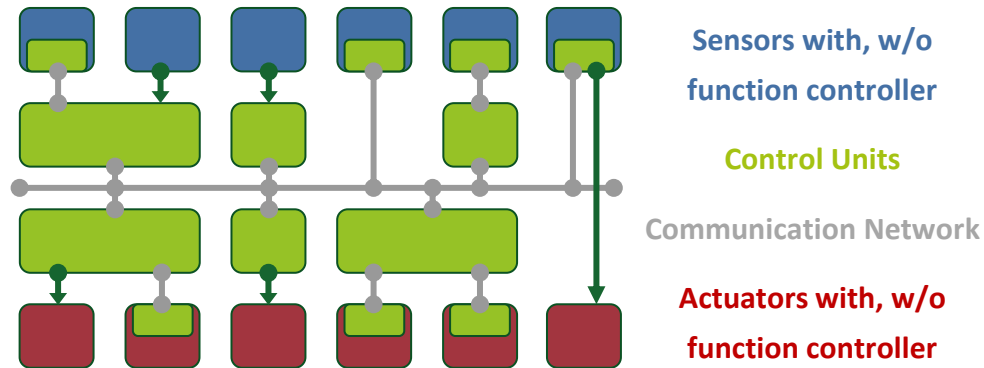


Architecture concepts

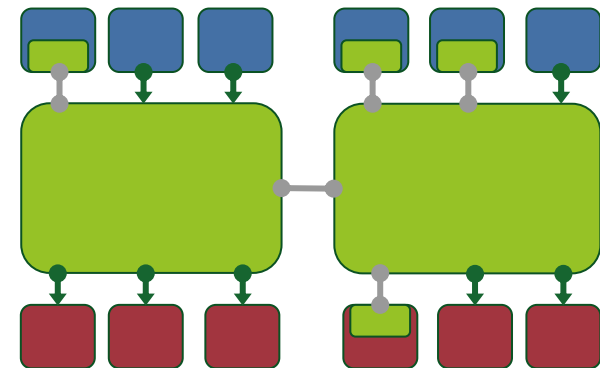
Domain controllers require new functional concepts



Function Controller



Domain Controller



- » One / a few SW functions per ECU
- » High HW complexity
- » High data communication
- » High integration effort for vehicle functions

- » More (central) SW functions per ECU
- » High SW complexity
- » Low data communication
- » Lower integration effort for vehicle functions

Features of the functional architecture for domain controllers

» Requirements

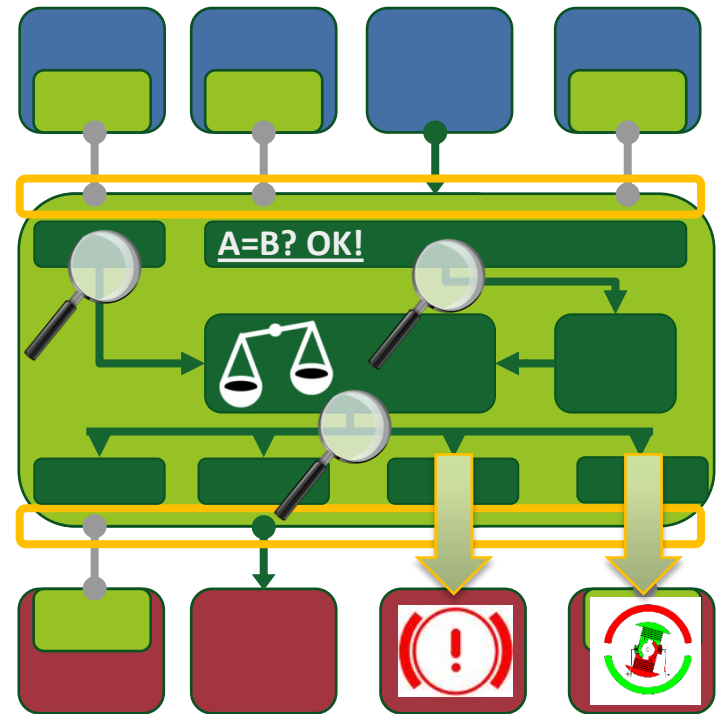
- › Scalability
- › Standardised interfaces
- › Hierarchic composition
- › Support of Functional Safety

» Prospects

- › Central parametrisation
- › Plausibility check of sensor data
- › Scenario specific actuator selection

» Application to the electric vehicle

- › Enabler for strategy change
- › Necessity for new functions
- › Efficiency and Safety

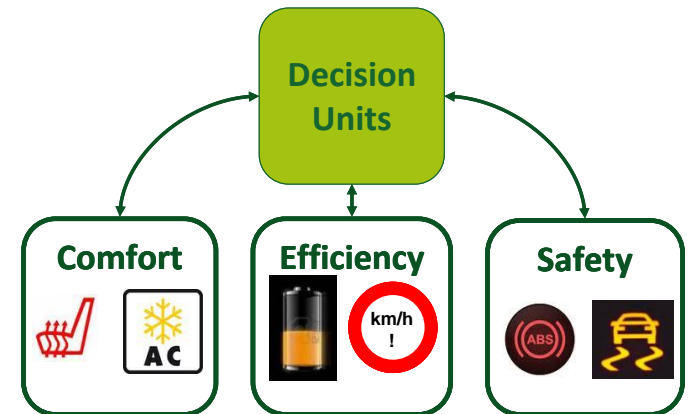
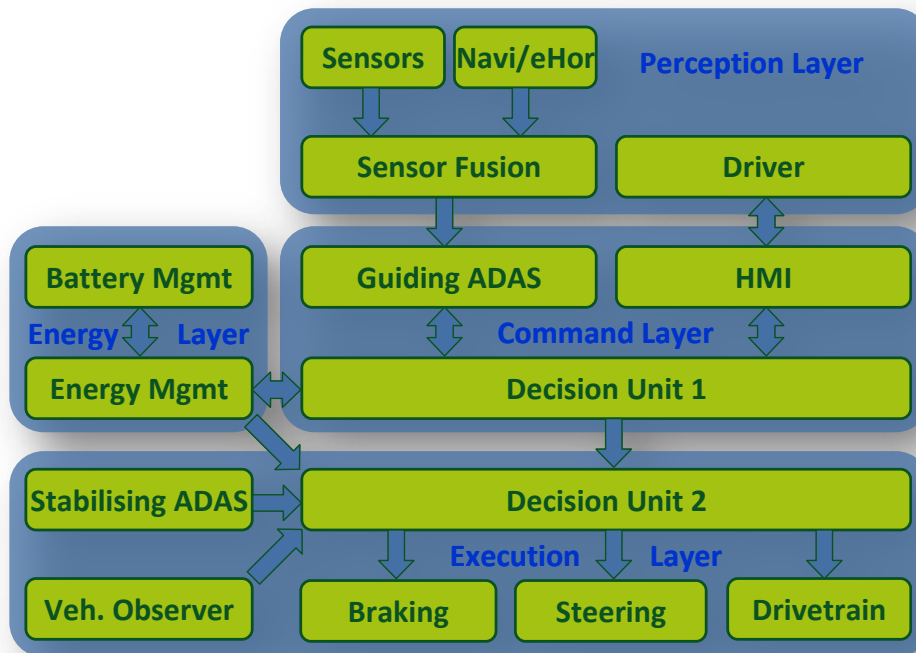


eFuture's compact functional architecture

...supports energy efficiency and safety

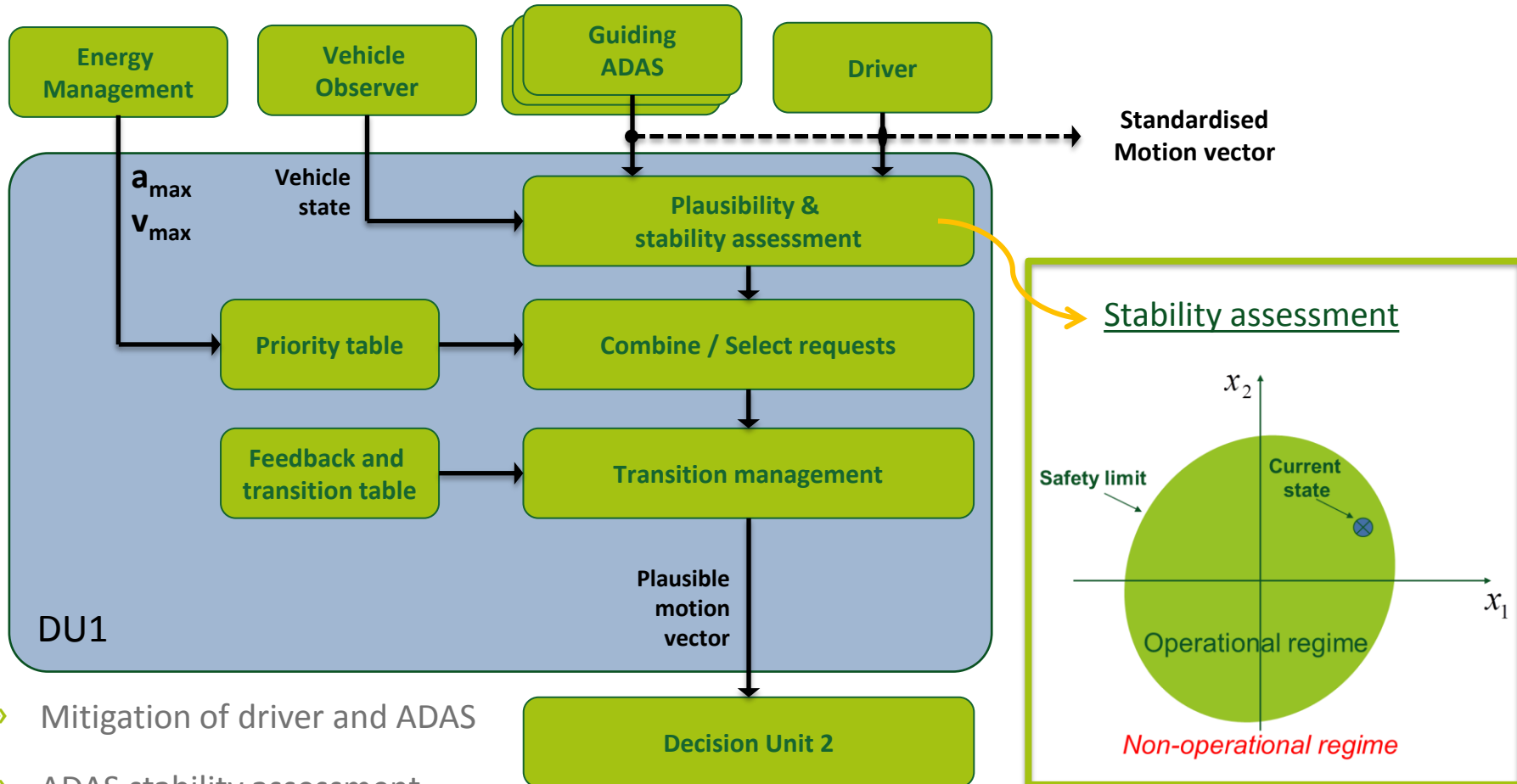


- » Introduction of decision units as central intelligence functions
- » Balancing of efficiency and comfort
- » Allowing for various new functions



Decision Unit 1: Command Layer

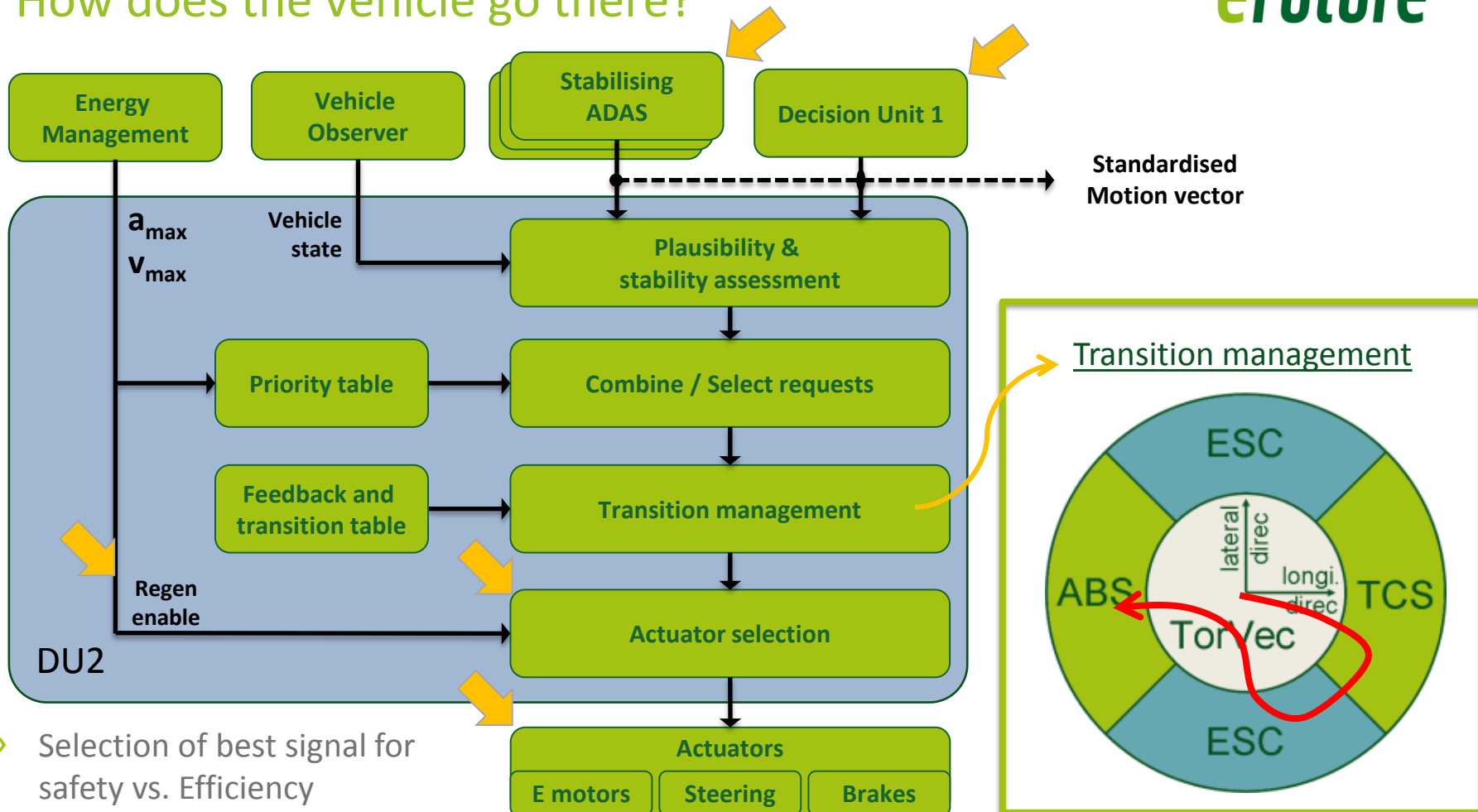
Where the vehicle shall drive to?



- » Mitigation of driver and ADAS
- » ADAS stability assessment
- » Transition management

Decision Unit 2: Execution Layer

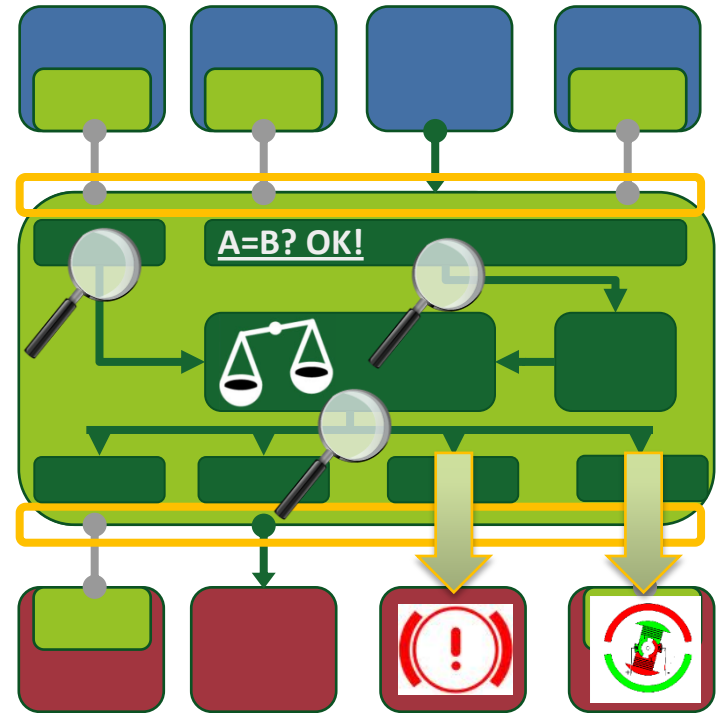
How does the vehicle go there?



- » Selection of best signal for safety vs. Efficiency
- » Selection of most suitable actuator

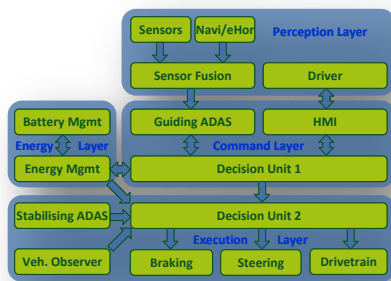
Features of the concept

- » Scalable function integration („Plug’n’Play“)
- » Vehicle behaviour follows simple parameters and rules set in priority tables
- » Redundant plausibility check for high ASIL ratings
- » Controlling the transition between manual and assisted driving

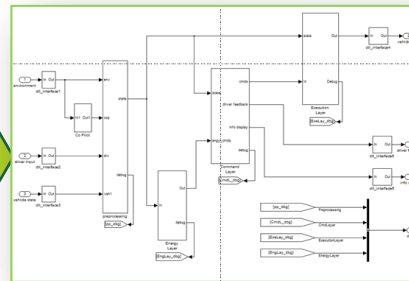


Vehicle Integration

- › Migration from simulation to the vehicle
- › Validation of the concept



Functional Architecture



Simulation Model



Lab Testing



Source: Hella



Demonstrator vehicle



Thank you for your attention.

Questions?

Simplified Architecture by the use of Decision Units

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